

TOPOLOGICAL CLASSIFICATION OF MAP GERMS USING REEB GRAPHS

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1. INTRODUCTION

The classification problem of singular points of C^∞ map germs is one of the most important problems in Singularity theory. The classical classification is done via \mathcal{A} -equivalence, where we take C^∞ -diffeomorphism germs in the source and the target. However, this is a difficult problem and it presents a lot of rigidity. Then it seems natural to investigate the classification of map germs up to weaker equivalence relations. Here we consider topological equivalence or C^0 - \mathcal{A} -equivalence, where the changes of coordinates are homeomorphisms instead of C^∞ -diffeomorphisms.

This work is devoted to the topological classification of C^∞ map germs from \mathbb{R}^3 to \mathbb{R}^2 which are finitely determined. The topological structure of a finitely determined map germ $f : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ is determined by the so-called link of f (cf. [6]). The link of f is obtained by taking a small enough representative $f : U \subset \mathbb{R}^3 \rightarrow \mathbb{R}^2$ and the intersection of its image with a small enough sphere S_δ^1 centered at the origin in \mathbb{R}^2 . When f has isolated zeros (i.e., $f^{-1}(0) = \{0\}$), the link is a stable map $\gamma : S^2 \rightarrow S^1$ and f is topologically equivalent to the cone of γ . As a consequence, two finitely determined map germs $f, g : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ are topologically equivalent if their associated links are topologically equivalent.

2. FINITE DETERMINACY AND THE LINK OF A MAP GERM

Two C^∞ map germs $f, g : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ are \mathcal{A} -equivalent if there exist C^∞ -diffeomorphism germs $\psi : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^3, 0)$ and $\phi : (\mathbb{R}^2, 0) \rightarrow (\mathbb{R}^2, 0)$ such that $f = \phi \circ g \circ \psi$. If ϕ, ψ are homeomorphisms instead of C^∞ -diffeomorphisms, then we say that f and g are *topologically equivalent* (or C^0 - \mathcal{A} -equivalent).

For simplicity, we will write just diffeomorphism instead of C^∞ -diffeomorphism.

We say that $f : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ is k -determined if for any map germ g with the same k -jet, we have that g is \mathcal{A} -equivalent to f . We say that f is finitely determined if it is k -determined for some k .

Let $f : U \rightarrow \mathbb{R}^2$ be a C^∞ map, where $U \subset \mathbb{R}^3$ is an open subset. We denote by $S(f) = \{p \in U \mid Jf(p) \text{ does not have rank } 2\}$ the *singular set* of f , where $Jf(p)$ is the Jacobian matrix of f . We also denote the *discriminant set* of f by $\Delta(f) = f(S(f))$.

Let $f : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ be a finitely determined map germ. Then there exists a representative $f : U \subset \mathbb{R}^3 \rightarrow \mathbb{R}^2$ such that

- i) $S(f) \cap f^{-1}(0) = \{0\}$,
- ii) the restriction $f|_{U - \{0\}}$ has only definite and indefinite simple fold singularities.

If f is finitely determined, then its discriminant $\Delta(f)$ is a plane curve with an isolated singularity at the origin. The number of half branches of $\Delta(f)$ will play a crucial role in

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the analysis of the Reeb graph associated to link of f and consequently, in the topological classification of f .

Denote by $J^r(n, p)$ the r -jet space from $(\mathbb{R}^n, 0)$ to $(\mathbb{R}^p, 0)$. For positive integers r and s with $s \geq r$, let $\pi_r^s : J^s(n, p) \rightarrow J^r(n, p)$ be the canonical projection defined by $\pi_r^s(j^s f(0)) = j^r f(0)$. For a positive number $\epsilon > 0$ we set

$$D_\epsilon^n = \{x \in \mathbb{R}^n \mid \|x\|^2 \leq \epsilon\}, \quad B_\epsilon^n = \{x \in \mathbb{R}^n \mid \|x\|^2 < \epsilon\} \text{ and } S_\epsilon^{n-1} = \{x \in \mathbb{R}^n \mid \|x\|^2 = \epsilon\}.$$

We denote D^n , B^n and S^{n-1} the standard disk, ball and sphere of radius 1, respectively.

T. Fukuda has proved the following cone structure theorem in his papers [5, 6]:

Theorem 2.1. *For any semialgebraic subset W of $J^r(n, p)$, there exist an integer s ($s \geq r$) depending only on n, p and r , and there exists a closed semialgebraic subset Σ_W of $(\pi_r^s)^{-1}(W)$ having codimension ≥ 1 such that for any C^∞ map $f : \mathbb{R}^n \rightarrow \mathbb{R}^p$ with $j^s f(0)$ belonging to $(\pi_r^s)^{-1}(W) \setminus \Sigma_W$ we have the following properties:*

- (A) **The case $f^{-1}(0) = \{0\}$:** *there is $\epsilon_0 > 0$ such that for any number ϵ with $0 < \epsilon \leq \epsilon_0$ we have:*
 - (A-i) *the set $\tilde{S}_\epsilon^{n-1} = f^{-1}(S_\epsilon^{p-1})$ is a C^∞ submanifold without boundary which is diffeomorphic to the standard unit sphere S^{n-1} .*
 - (A-ii) *The restricted map $f|_{\tilde{S}_\epsilon^{n-1}} : \tilde{S}_\epsilon^{n-1} \rightarrow S_\epsilon^{p-1}$ is topologically stable (C^∞ stable if (n, p) is a nice pair in Mather's sense).*
 - (A-iii) *If $\tilde{D}_\epsilon^{n-1} = f^{-1}(D_\epsilon^{p-1})$, then the restricted map $f|_{\tilde{D}_\epsilon^{n-1}} : \tilde{D}_\epsilon^{n-1} \rightarrow D_\epsilon^p$ is topologically equivalent to the cone of $f|_{\tilde{S}_\epsilon^{n-1}}$.*
- (B) **The case $f^{-1}(0) \neq \{0\}$:** *there exist a positive number ϵ_0 and a strictly increasing C^∞ function $\delta : [0, \epsilon_0] \rightarrow [0, \infty)$ with $\delta(0) = 0$ such that for every ϵ and δ with $0 < \epsilon \leq \epsilon_0$ and $0 < \delta \leq \delta(\epsilon)$ we have:*
 - (B-i) *$f^{-1}(0) \cap S_\epsilon^{n-1}$ is an $(n - p - 1)$ -dimensional manifold and it is diffeomorphic to $f^{-1}(0) \cap S_{\epsilon_0}^{n-1}$.*
 - (B-ii) *$D_\epsilon^n \cap f^{-1}(S_\delta^{p-1})$ is a C^∞ manifold, in general with boundary and it is diffeomorphic to $D_{\epsilon_0}^n \cap f^{-1}(S_{\delta(\epsilon_0)}^{p-1})$.*
 - (B-iii) *the restriction $f|_{D_\epsilon^n \cap f^{-1}(S_\delta^{p-1})} : D_\epsilon^n \cap f^{-1}(S_\delta^{p-1}) \rightarrow S_\delta^{p-1}$ is a topologically stable map (C^∞ stable if (n, p) is a nice pair in Mather's sense) and its topological class is independent of ϵ and δ .*

Assuming that f is r -determined for some r and taking $W = \{j^r f(0)\}$, we can apply Theorem 2.1 to obtain a representative of f satisfying (A) or (B), depending on if $f^{-1}(0) = \{0\}$ or $f^{-1}(0) \neq \{0\}$. Note that when $n \leq p$ we always have $f^{-1}(0) = \{0\}$ but when $n > p$ we may have the two possibilities.

Definition 2.2. Let $f : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ be a finitely determined map germ such that $f^{-1}(0) = \{0\}$. We say that the stable map $f|_{\tilde{S}_\epsilon^2} : \tilde{S}_\epsilon^2 \rightarrow S_\epsilon^1$ is the *link* of f , where f is a representative that satisfies the Fukuda's conditions (A) of Theorem 2.1 adapted for case $n = 3$ and $p = 2$.

Corollary 2.3. *Two finitely determined map germs $f, g : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ with $f^{-1}(0) = \{0\} = g^{-1}(0)$ are topologically equivalent if their associated links are topologically equivalent.*

3. THE GENERALIZED REEB GRAPH

The Reeb graph was introduced by Reeb in [7] and it is well known that it is a complete topological invariant for Morse functions from S^2 to \mathbb{R} (see [1]).

Proposition 3.1. *Let $\gamma : S^2 \rightarrow S^1$ be a stable map. Then γ is not a regular map.*

Given a continuous map $f : X \rightarrow Y$ between topological spaces, we consider the following equivalence relation on X : $x \sim y \Leftrightarrow f(x) = f(y)$ and x and y are in the same connected component of $f^{-1}(f(x))$.

Proposition 3.2. *Let $\gamma : S^2 \rightarrow S^1$ be a stable map. Then the quotient space S^2 / \sim admits the structure of a connected graph in the following way:*

- (1) *the vertices are the connected components of level curves $\gamma^{-1}(v)$, where $v \in S^1$ is a critical value;*
- (2) *each edge is formed by points that correspond to connected components of level curves $\gamma^{-1}(v)$, where $v \in S^1$ is a regular value.*

Each vertex of the graph can be of three topological types, depending on if the connected component has a maximum/minimum critical point, a saddle point or just regular points.

Let $v_1, \dots, v_r \in S^1$ be the critical values of γ . We choose a base point $v_0 \in S^1$ and an orientation. We can reorder the critical values such that $v_0 \leq v_1 < \dots < v_r$ and we label each vertex with the index $i \in \{1, \dots, r\}$, if it corresponds to the critical value v_i .

Definition 3.3. The graph given by S^2 / \sim together with the labels of the vertices, as previously defined, is said to be the *generalized Reeb graph* associated to $\gamma : S^2 \rightarrow S^1$.

For simplicity, from now on we will just call Reeb graph to the generalized Reeb graph, unless otherwise specified.

Proposition 3.4. *Let $\gamma : S^2 \rightarrow S^1$ be a stable map. Then the Reeb graph of γ is a tree.*

Let $\gamma, \delta : S^2 \rightarrow S^1$ be two stable maps. Let Γ_γ and Γ_δ be their respective Reeb graphs. Consider the induced quotient maps $\bar{\gamma} : \Gamma_\gamma \rightarrow S_\gamma^1$ and $\bar{\delta} : \Gamma_\delta \rightarrow S_\delta^1$, where S_γ^1, S_δ^1 denote S^1 with the graph structure whose vertices are the critical values of γ, δ respectively.

Definition 3.5. An *isomorphism* between two graphs Γ_1 and Γ_2 is a bijection f from $V(\Gamma_1)$ to $V(\Gamma_2)$ such that two vertices v and w are adjacent in Γ_1 if and only if $f(v)$ and $f(w)$ are adjacent in Γ_2 , where $V(\Gamma_i) = \{\text{vertices of } \Gamma_i\}$.

Definition 3.6. We say that Γ_γ is *equivalent* to Γ_δ and we denote it by $\Gamma_\gamma \sim \Gamma_\delta$, if there exist graph isomorphisms $j : \Gamma_\gamma \rightarrow \Gamma_\delta$ and $l : S_\gamma^1 \rightarrow S_\delta^1$, such that the following diagram is commutative:

$$\begin{array}{ccc} V_\gamma & \xrightarrow{\bar{\gamma}|_{V_\gamma}} & \Delta_\gamma \\ j|_{V_\gamma} \downarrow & & \downarrow l|_{\Delta_\gamma} \\ V_\delta & \xrightarrow{\bar{\delta}|_{V_\delta}} & \Delta_\delta \end{array}$$

where $V_\gamma = \{\text{vertices of } \Gamma_\gamma\}$, $V_\delta = \{\text{vertices of } \Gamma_\delta\}$ and Δ_γ and Δ_δ are their respective discriminant sets.

Theorem 3.7. *Let $\gamma, \delta : S^2 \rightarrow S^1$ be two stable maps. If γ and δ are topologically equivalent then their respective Reeb graphs are equivalent.*

The above theorem allows us to extend the definition of Reeb graph for C^0 -stable maps between topological spheres.

Theorem 3.8. *Let $\gamma, \delta : S^2 \rightarrow S^1$ be two stable maps such that $\Gamma_\gamma \sim \Gamma_\delta$. Then γ is \mathcal{A} -equivalent to δ .*

Corollary 3.9. *Let $\gamma, \delta : S^2 \rightarrow S^1$ be two stable maps. Then the following statements are equivalent:*

- (1) γ, δ are \mathcal{A} -equivalent,
- (2) γ, δ are topologically equivalent,
- (3) $\Gamma_\gamma \sim \Gamma_\delta$.

Theorem 3.10. *Let $f, g : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ be two finitely determined map germs such that $f^{-1}(0) = \{0\} = g^{-1}(0)$. If f and g are topologically equivalent then the Reeb graphs of their links are equivalent.*

Again, Theorem 3.10 together with Corollary 2.3 and Theorem 3.8 show that the Reeb graph is a complete topological invariant for map germs from with isolated zeros.

Corollary 3.11. *Let $f, g : (\mathbb{R}^3, 0) \rightarrow (\mathbb{R}^2, 0)$ be finitely determined map germs such that $f^{-1}(0) = \{0\} = g^{-1}(0)$. Then the following statements are equivalent:*

- (1) f, g are topologically equivalent,
- (2) the Reeb graphs of the links of f, g are equivalent,
- (3) the links of f, g are topologically equivalent.

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