

Kaluza-Klein理論

と

QED

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$N^6 \supset L^5$

$R^2 = \mathbb{C}$

\cup

$S^1 = U(1)$



重力場

(3,3)型



メカニクス
電磁場
電子場

M^4



重力場, 電磁場

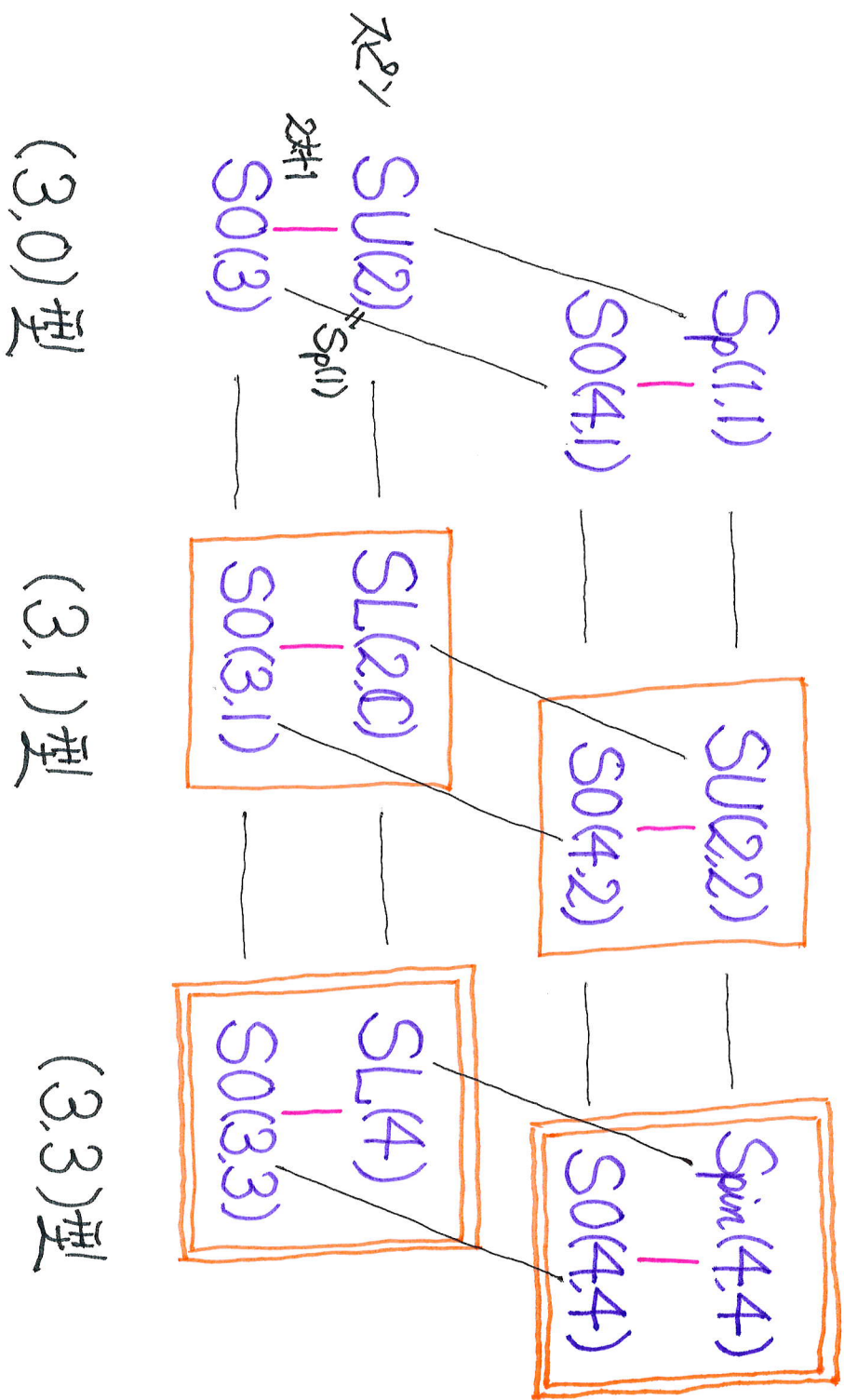
(3,1)型

* Kaluza (1919), Klein (1926)

* Kostant (1988), MIT

conformal group
(massless 粒子)

isometry group
(massive 粒子)



(3,0)型

(3,1)型

(3,3)型

ここでは

- 光, 電子, 陽電子の3対性



cf. 双対性

*超対称性 ポジツ \leftrightarrow ネグツ

10次元, 4次元, 2次元

*超弦理論

S双対, T双対

AdS-CFT双対

- 伝播関数, S行列, Feynman積分における

発散積分の正則化 ツイック-積分表示

cf. 4次元

6次元において!

6次元において!

4次元(3,1)型時空

$$R^4: x = (x^0, x^1, x^2, x^3)$$

4次元 Minkowski 空間

$$(3,1) \text{ 型 } g = (g_{\mu\nu}) = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

$$ds^2 = (dx^0)^2 - (dx^1)^2 - (dx^2)^2 - (dx^3)^2$$

$$\square = \left(\frac{\partial}{\partial x^0}\right)^2 - \left(\frac{\partial}{\partial x^1}\right)^2 - \left(\frac{\partial}{\partial x^2}\right)^2 - \left(\frac{\partial}{\partial x^3}\right)^2$$

1) スカラー場 $\mathcal{G}(x)$ ($\square + m^2$) $\mathcal{G} = 0$ Klein Gordon eq.

2) 電磁場 $A(x) = \sum_{n=0}^3 A_n(x) dx^n$ (光子場)

$$\begin{cases} \square A_n = 0 & (n=0,1,2,3) & \text{波動方程式} \\ \sum_{n=0}^3 \frac{\partial A_n}{\partial x^n} = 0 & & \text{Lorentz 条件} \end{cases}$$

3) 電子場 $\psi(x) = \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \\ \psi_3(x) \\ \psi_4(x) \end{pmatrix}$ (スピノル場)

$$\left(\sum_{\nu=0}^3 \gamma^\nu \frac{\partial}{\partial x^\nu} + m \right) \psi = 0 \quad \text{Dirac eq.}$$

SL(2,C) の表現空間 $\gamma^\nu: 4 \times 4$ のガンマ行列

$SO(3,1)$ -不変 $\left\{ \begin{array}{l} \text{6次元} \\ \text{Lorentz 群} + \text{平行移動} = \text{Poincaré 群} \\ \text{回転} + \text{ブースト} \end{array} \right.$

$m=0$ massless $\left\{ \begin{array}{l} \text{15次元} \\ \text{共形群} = \text{Poincaré 群} + \text{相似変換} + \text{反転} \end{array} \right.$

$$SO(4,2) = \{SO(3,1) \cdot R U_5\}$$

SO(p, 2) の Bruhat 分解

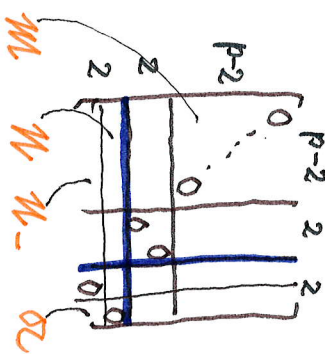
p=4, SO(4, 2)

$$G = SO(p, 2) = \{g \in GL(p+2) \mid \text{tg} J g = J\}$$

$$J = \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & -1 & & \\ & & & & \ddots & \\ & & & & & -1 \end{bmatrix} \sim I_{p, 2} = \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & -1 & & \\ & & & & \ddots & \\ & & & & & -1 \end{bmatrix}$$

$$\mathfrak{g} = \sigma(p, 2) = \{X \in \mathfrak{gl}(p+2) \mid \text{t}XJ + JX = 0\}$$

$$= \mathfrak{M} \oplus \mathfrak{A} \oplus \mathfrak{N} \oplus \mathfrak{N}_-$$



$$G \cong \text{MANN}_- \cup \text{MAN} \cup \text{N}_-$$

$$\cong \underbrace{\text{MANN}_-}_P \cong SO(p-1, 1) \cdot \mathbb{R}_+ \cdot \mathbb{R}_+ \cdot \mathbb{R}_+ \cdot \mathbb{R}_+$$

$$\mathfrak{M} = \begin{bmatrix} \hat{m} & \\ & 1_2 \end{bmatrix}, \mathfrak{A} = \begin{bmatrix} 1_p & \\ & \text{t}x \end{bmatrix}$$

$$\mathfrak{N}_+ = \begin{bmatrix} 1_{p-2} & & & \\ & 1_2 & & \\ & & 1_1 & \\ & & & 1_1 \end{bmatrix}, \mathfrak{N}_- = \begin{bmatrix} 1_{p-2} & & & \\ & 1_2 & & \\ & & 1_1 & \\ & & & 1_1 \end{bmatrix}$$

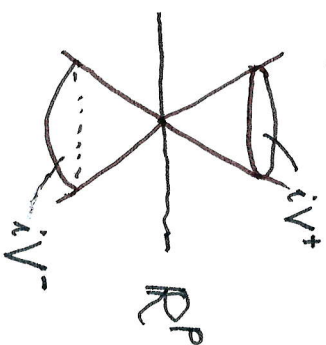
$$\mathfrak{N}_+ = \begin{bmatrix} 1_{p-2} & & & \\ & 1_2 & & \\ & & 1_1 & \\ & & & 1_1 \end{bmatrix}, \mathfrak{N}_- = \begin{bmatrix} 1_{p-2} & & & \\ & 1_2 & & \\ & & 1_1 & \\ & & & 1_1 \end{bmatrix}$$

$$\underline{N_-} \cong \mathbb{R}^p \subset \mathbb{Q}^p = \mathfrak{p} / \mathfrak{g} \cong S^p \times S^1$$

$$T^\pm = \frac{SO(p, 2)}{SO(p) \times SO(2)} \cong \mathbb{R}^p \times iV^\pm$$

$$[y, y] > 0, y^0 \geq 0$$

IV 型 対称有界領域
Silov 境界が \mathbb{Q}^p



SO(p, 2) の R^p への作用

$$x \in N_+ = \mathbb{R}^p \subset \mathbb{Q}^p$$

$$x \in$$

$$\begin{bmatrix} 1 & & & & & \\ & 1_{p-2} & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & x_1 & \\ & & & & & x_2 \end{bmatrix}$$

$$\frac{1}{2} [x, x] = -\frac{1}{2} (|x|^2 + 2x_1 x_2)$$

$$g \in SO(p, 2)$$

$$(x \cdot g)_k = \sum_{j=1}^p x_j g_{jk} + \frac{1}{2} [x, x] g_{pk} + g_{pk}$$

$$\frac{\text{分子}}{\text{分母}} \approx \delta(x, g)$$

2次分数変換

$$\left(\det \left(\frac{\partial(x \cdot g)}{\partial x} \right) \right)^{-1} = \delta(x, g)^{-1}$$

$$\frac{\partial(x \cdot g)}{\partial x} = \hat{m}(x, g) \delta(x, g)^{-1}$$

SO(p-1, 1)

- $M \cong SO(p-1, 1) \ni g = \begin{bmatrix} \hat{g} & \\ & 1 \end{bmatrix}$

$$(x \cdot g)_k = \sum_{j=1}^p x_j g_{jk}$$

- $A \ni g = \begin{bmatrix} 1 & & \\ & 1 & \\ & & e^{2t} \end{bmatrix}$

$$(x \cdot g)_k = \frac{1}{e^t} x^k \quad \text{相似変換}$$

- $N_- \ni g$

$$(x \cdot g)_k = x^k + g^k \quad \text{平行移動}$$

$$\sigma = \begin{bmatrix} 1 & & & & & \\ & 1_{p-2} & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{bmatrix}$$

$$\sigma^2 = 1$$

Weyl群元 反転

$$\begin{cases} x'_k = \frac{x_k}{[x, x]_2} = \frac{2x_k}{[x, x]} & 1 \leq k \leq p-2 \\ x'_{p-1} = \frac{2x_p}{[x, x]} \\ x'_p = \frac{2x_{p-1}}{[x, x]} \end{cases}$$

* $SL(2, \mathbb{C})$ と $SO(3, 1)$ の関係

• $H(2) = \{Z \in M_2(\mathbb{C}) \mid Z^* = Z\}$ Hermitian 行列

$R \in SL(2, \mathbb{C})$ に対して, $Z \mapsto D(R)Z := RZR^*$

• Pauli の σ 行列 $\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $\sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$, $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $\sigma_4 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ $H(2)$ の基底

$$H(2) \ni Z = \begin{pmatrix} x_3 + x_4 & x_1 - ix_2 \\ x_1 + ix_2 & -x_3 + x_4 \end{pmatrix} = \sum_{j=1}^4 x_j \sigma_j$$

• $\phi: H(2) \ni Z = \sum_{j=1}^4 x_j \sigma_j \mapsto x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \in \mathbb{R}^4$ $\phi(D(R)Z) = D(R)\phi(Z) = D(R)x$

$$H(2) \ni Z \xrightarrow{R} D(R)Z \in H(2)$$

$$\begin{array}{ccc} \mathbb{R}^4 \ni x = \phi(Z) & \xrightarrow{D(R)} & D(R)x = \phi(D(R)Z) \in \mathbb{R}^4 \\ \phi \downarrow & \cong & \downarrow \phi \\ \mathbb{R}^4 \ni x = \phi(Z) & \xrightarrow{D(R)} & D(R)x = \phi(D(R)Z) \in \mathbb{R}^4 \end{array}$$

* $\det Z = -x_1^2 - x_2^2 - x_3^2 + x_4^2$ であり, $\det(RZR^*) = \det Z$

\mathbb{R}^4 上の $\langle x, x \rangle = -x_1^2 - x_2^2 - x_3^2 + x_4^2$ であり, $D(R)$ によって不変

* $D: SL(2, \mathbb{C}) \ni R \mapsto D(R) \in SO(3, 1)$

$\ker D = \pm I_2$

• $Z = \sum_{j=1}^4 x_j \sigma_j$, $g \in D(R)$ に対して

$$D(R)Z = RZR^* = \sum_{j=1}^4 x_j \sigma_j = (\sigma_1 \sigma_2 \sigma_3 \sigma_4) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = (\sigma_1 \sigma_2 \sigma_3 \sigma_4) g \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

よって, $(R\sigma_1 R^*, R\sigma_2 R^*, R\sigma_3 R^*, R\sigma_4 R^*) = (\sigma_1 \sigma_2 \sigma_3 \sigma_4) g$

○ 誘導表現

$\rho: \text{MAN} \rightarrow \text{GL}(V)$ 表現
 $\rho = \rho_{\text{MAN}}$ (MAN) \rightarrow $\rho_{\text{GL}(V)}$ (GL(V))

$\rho = \rho_{\text{SO}(p,q)}: \text{M} \rightarrow \text{GL}(V)$ Lorentz 表現

- 1) trivial
- 2) ベクトル表現 $V = \mathbb{R}^p$
- 3) スピン表現 $\frac{1}{2}$

誘導表現

$$\Gamma(\text{MAN}, G, G \times V) \cong \Gamma(\mathbb{R}^p, V)$$

- 1) $\rho: \text{trivial}$ スカラー場
- 2) $\rho: \text{ベクトル}$ ベクトル場, 電磁場
- 3) $\rho: \text{スピノール}$ スピノール場, 電子場

* $G \supset H$

$\left\{ \begin{array}{l} G \text{ の表現} \rightarrow H \text{ の表現} \\ H \text{ の表現} \rightarrow G \text{ の表現} \end{array} \right.$

表現の制限
誘導表現

H の V への表現
 G の等質ベクトル束 $G \times V \rightarrow G/H$ への作用
 G の $\Gamma(G \times V)$ への表現

$g \in G$

$$(\text{T}_g \rho)(x) = \rho(\text{M}(x, g)) \rho(x, g) \delta(x, g)^{-\frac{p}{2}}$$

$$\cdot \text{dot} \left(\frac{\partial(x, g)}{\partial x} \right) = \delta(x, g)^{-p}$$

$$\cdot (\text{T}_g, \rho(x))$$

※ Poisson 变换 P

cf. 複素関数論, 諸和関数
Poisson 積表示

○ Poisson 核 $P_{\mu, \nu}(w, \eta) = \frac{1}{[w - \eta, w - \bar{\eta}]^{\frac{\mu}{2}}} \left(\frac{[w - \bar{w}, w - \bar{\eta}]^{\frac{\mu}{2}}}{[w - \eta, w - \eta]} \right)^{\nu}$

$w \in T = \mathbb{R}^p + iV^p$
 $\eta \in \mathbb{R}^p$

* $P_{\mu, \nu}(w, g, \eta, g) = P_{\mu, \nu}(w, \eta) S(w, g)^{\frac{\mu}{2}} S(\eta, g)^{\frac{\mu + \nu}{2}}$

○ Poisson 变换 $(P\phi)(w) = \int_{\mathbb{R}^p} P_{\mu, \nu}(w, \eta) \phi(\eta) d\eta$

○ $\nu = 0$ とする. cf. $\mu = 0$

$\phi \in \mathcal{D}_{-\frac{p}{2} - \lambda} \Rightarrow (T\phi)(w) = \phi(w, g) S(w, g)^{-\frac{p}{2} - \lambda}$

* Poisson 变换 P に対し,

$\lambda = -1$ とする

$P: \mathcal{D}_{-\frac{p}{2} - 1} \longrightarrow \mathcal{D}_{-\frac{p}{2} + 1}$
 $P: \mathcal{D}_{-\frac{p}{2} + \lambda} \longrightarrow \mathcal{D}_{-\frac{p}{2} - \lambda}$

$(P\phi)(w) = \int_{\mathbb{R}^p} \frac{1}{[w \pm \eta, w \pm \eta]^{\frac{p-2}{2}}} \phi(\eta) d\eta$

図式

自由場

※ 遷移作用素 (matrix も可換)

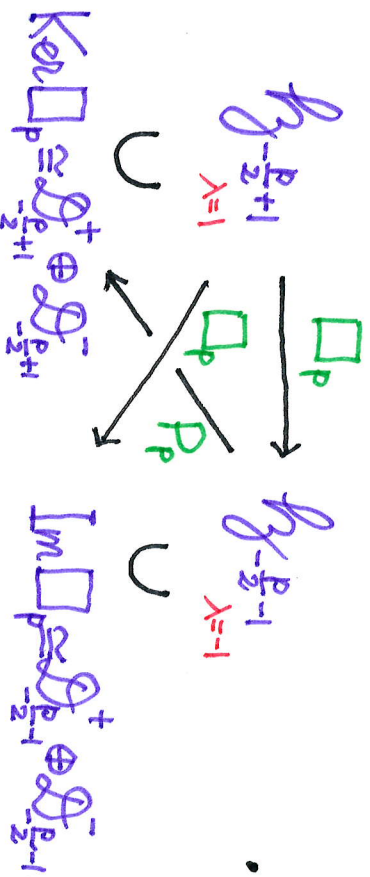
$$S: V \xrightarrow{T_g} V'$$

* $\text{Ker } S, \text{Im } S$ は表現部分空間

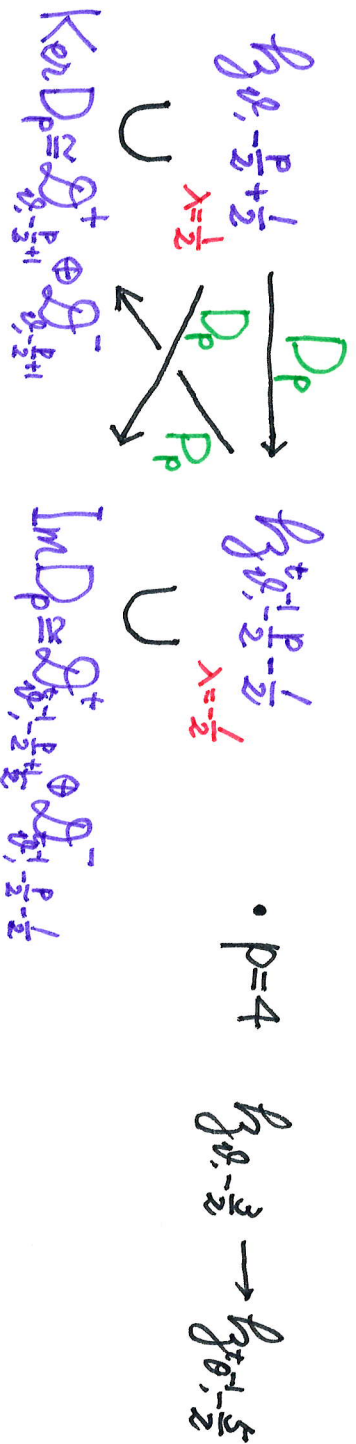
• スカラー場

(ベクトル場と同様)

• $p=4 \quad h_{g^{-1}} \rightarrow h_{g^{-3}}$



• スピノル場



相互作用

QED (量子電磁力学) U(1)-ゲージ理論

$$\mathcal{L} = \bar{\psi} (i\gamma^\mu \underline{D}_\mu - m) \psi - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

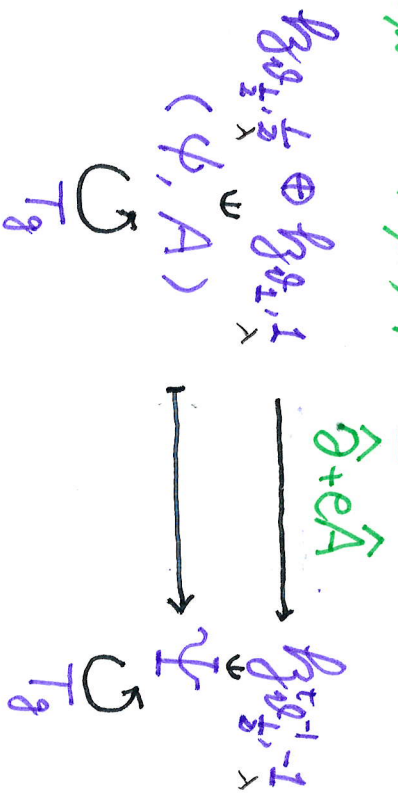
$\xrightarrow{\text{Lorentz ゲージ}}$ $\frac{1}{2} \partial_\mu A_\nu \partial^\mu A^\nu$

$$= \bar{\psi} (i\gamma^\mu \partial_\mu - m) \psi - e \bar{\psi} \gamma^\mu A_\mu \psi - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

$\xrightarrow{\text{Feynman}} \frac{1}{2} \partial_\mu A_\nu \partial^\mu A^\nu$

$$\begin{cases} (i\gamma^\mu \partial_\mu + e\gamma^\mu A_\mu) \psi = 0 \\ \square A^\mu = e \bar{\psi} \gamma^\mu \psi \end{cases}$$

$$(i\gamma^\mu \partial_\mu + e\gamma^\mu A_\mu) \psi = \Psi$$



Kerは?

解は?

$$\partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\nu)} \right) = \partial_\mu (i\bar{\psi} \gamma^\mu \psi), \quad \frac{\partial \mathcal{L}}{\partial A_\mu} = -e \bar{\psi} \gamma^\mu \psi - m\bar{\psi} \psi$$

$$\begin{aligned} \therefore i\gamma^\mu \partial_\mu \psi - m\psi &= e\gamma^\mu A_\mu \psi \\ m=0 \text{ on } \mathbb{R}^4 & \\ \underline{i\gamma^\mu \partial_\mu + e\gamma^\mu A_\mu} \psi &= 0 \\ e=0 \text{ on } \mathbb{R}^4 & \\ i\gamma^\mu \partial_\mu \psi &= 0 \text{ (自由場)} \end{aligned}$$

$$\partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\nu)} \right) = \partial_\mu (\partial^\mu A^\nu - \partial^\nu A^\mu), \quad \frac{\partial \mathcal{L}}{\partial A_\mu} = -e \bar{\psi} \gamma^\mu \psi$$

$$\begin{aligned} \therefore \underline{\partial_\nu F^{\mu\nu}} &= e \bar{\psi} \gamma^\mu \psi \\ \square A^\mu &= 0 \text{ (自由場)} \\ \partial_\mu A^\mu &= 0 \end{aligned}$$

6次元(3,3)型時空

SO(4,4)のBruhat分解

$$G = SO(4,4) = \{g \in GL(8) \mid {}^t g J g = J\}$$

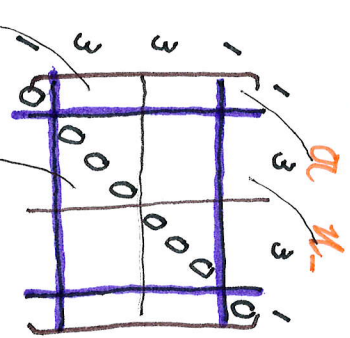
$$\mathfrak{g} = \mathfrak{o}(4,4) = \{X \in \mathfrak{gl}(8) \mid {}^t X + JX = 0\}$$

28次元

$$= \mathfrak{m} \oplus \mathfrak{a} \oplus \mathfrak{n} \oplus \mathfrak{n}_-$$

$\begin{matrix} \mathfrak{SO}(3,3) & & & & & & & \\ \downarrow & & & & & & & \\ \mathfrak{M} & & \mathfrak{A} & & \mathfrak{N} & & \mathfrak{N}_- \end{matrix}$

$$J = \begin{bmatrix} & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \end{bmatrix} \sim I_{3,3} = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & -1 \\ & & & & -1 \\ & & & & & -1 \end{bmatrix}$$



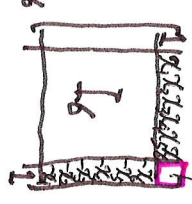
$$-Q(x) = -(x_1 x_2 + x_2 x_3 + x_3 x_4)$$

$$G = \text{MANN_UMANN_N}$$

$$\cong \underbrace{\text{MANN}}_P \cong \text{SO}(3,3) \cdot \mathbb{R}_+ \cdot \mathbb{R}^6 \cdot \mathbb{R}^6$$

$$\underline{N} \cong \mathbb{R}^6 \subset \mathbb{Q}^6 = \underbrace{P}_G \cong \text{SO}(3,3) \times \mathbb{Z}_2$$

$$m = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}, \quad \mathfrak{a} = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}, \quad \mathfrak{n} = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}$$



$$\sigma = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix} \in \text{SO}(4,4)$$

反転

$$G = \{ \text{SO}(3,3) \cdot \mathbb{R} \cup \sigma \}$$

SO(4,4) on \mathbb{R}^6 action

$$x \in N_- = \mathbb{R}^6 \subset \mathbb{Q}^6$$

$$g \in \text{SO}(4,4)$$

$$g: x \mapsto x' = xg$$

$$x'_k = \frac{g_{0k} + \sum_{j=1}^4 x_j g_{jk} - Q(x) g_{7k}}{g_{00} + \sum_{j=1}^4 x_j g_{j0} - Q(x) g_{70}}$$

$1 \leq k \leq 6$

二次分数变换

$$\cdot M \cong \text{SO}(3,3) \ni g = \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{bmatrix}$$

$$x'_k = x_k \tilde{g}_{kj}$$

$$x'_j = \sum_{k=1}^6 x_k \tilde{g}_{kj}$$

$$\cdot A \ni g = \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{bmatrix}$$

$x' = \tau x$ 相似变换

$$\odot \sigma = \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{bmatrix}$$

$\sigma^2 = 1$ 反卷

$$\cdot \begin{cases} x'_k = x_k \\ x'_k = \frac{x_{7-k}}{Q(x)} \end{cases} \quad (1 \leq k \leq 6)$$

$$[dx', dx'] = \frac{1}{Q(x)^2} [dx, dx]$$

※ $SL(4)$ と $SO(3,3)$ の関係

○ $A(4) = \{X \in M_4(\mathbb{R}) \mid {}^tX = -X\}$ 交代行列

$u \in SL(4)$ に対して, $X \mapsto {}^t u X u$

○ $A(4) \ni X = \begin{pmatrix} 0 & -x_1 & x_2 & -x_3 \\ x_1 & 0 & -x_4 & -x_5 \\ -x_2 & x_4 & 0 & -x_6 \\ x_3 & x_5 & x_6 & 0 \end{pmatrix} = \sum_{k=1}^6 x_k \Gamma^k = (x_1 x_2 x_3 x_4 x_5 x_6) \begin{pmatrix} \Gamma^1 \\ \Gamma^2 \\ \Gamma^3 \\ \Gamma^4 \\ \Gamma^5 \\ \Gamma^6 \end{pmatrix}$

○ $A(4) \ni X \xrightarrow{u \in SL(4)} X' = {}^t u X u$

$\mathbb{R}^6 \ni x \xrightarrow{\tilde{u} \in SO(3,3)} x' = x \tilde{u}$

○ ${}^t u X u = {}^t u \left(\sum_{k=1}^6 x_k \Gamma^k \right) u = \sum_{k=1}^6 x_k {}^t u \Gamma^k u = (x_1 x_2 x_3 x_4 x_5 x_6) \begin{pmatrix} \Gamma^1 \\ \Gamma^2 \\ \Gamma^3 \\ \Gamma^4 \\ \Gamma^5 \\ \Gamma^6 \end{pmatrix}$

$= \sum_{k=1}^6 x'_k \Gamma^k = (x'_1 x'_2 x'_3 x'_4 x'_5 x'_6) \begin{pmatrix} \Gamma^1 \\ \Gamma^2 \\ \Gamma^3 \\ \Gamma^4 \\ \Gamma^5 \\ \Gamma^6 \end{pmatrix}$

$= (x_1 x_2 x_3 x_4 x_5 x_6) \tilde{u}$

ガンマ行列

$\Gamma^1 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}, \Gamma^2 = \begin{pmatrix} 0 & 0 & 1 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \Gamma^3 = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$

$\Gamma^4 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \Gamma^5 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \Gamma^6 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

$\det X = (p5X)^2 = (x_1 x_6 + x_2 x_5 + x_3 x_4)^2 \tau^{-1}$

$\det ({}^t u X u) = \det X$

\mathbb{R}^6 上の $\langle x, x \rangle = x_1 x_6 + x_2 x_5 + x_3 x_4 \tau^{-1}$

\tilde{u} は不変

$\begin{pmatrix} {}^t u \Gamma^1 u \\ {}^t u \Gamma^2 u \\ {}^t u \Gamma^3 u \\ {}^t u \Gamma^4 u \\ {}^t u \Gamma^5 u \\ {}^t u \Gamma^6 u \end{pmatrix}$

+

○ スカラ場 $\phi(x) \rightarrow (T_u \phi)(x) = \phi(x; \tilde{u})$

・ ベクトル場 $A(x) = \sum_{n=1}^k A_n(x) dx_n = \begin{bmatrix} A_1(x) \\ A_2(x) \\ A_3(x) \\ A_4(x) \\ A_5(x) \\ A_6(x) \end{bmatrix} \rightarrow (T_u A)(x) = \tilde{u} A(x; \tilde{u})$

・ スピノル場 $\psi(x) = \begin{bmatrix} \psi_1(x) \\ \psi_2(x) \\ \psi_3(x) \\ \psi_4(x) \end{bmatrix} \rightarrow (T_u \psi)(x) = U \cdot \psi(x; \tilde{u})$

○ $\Gamma^k := \Gamma^k$

$$\begin{bmatrix} \Gamma^1 \\ \Gamma^2 \\ \Gamma^3 \\ \Gamma^4 \\ \Gamma^5 \\ \Gamma^6 \end{bmatrix} = \begin{bmatrix} \Gamma^1 \\ \Gamma^2 \\ \Gamma^3 \\ \Gamma^4 \\ \Gamma^5 \\ \Gamma^6 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & -x_1 & x_2 & -x_3 \\ x_1 & 0 & -x_4 & -x_5 \\ -x_2 & x_4 & 0 & -x_6 \\ x_3 & x_5 & x_6 & 0 \end{bmatrix}, X' = \begin{bmatrix} 0 & -x_6 & x_5 & -x_4 \\ x_6 & 0 & -x_3 & -x_2 \\ -x_5 & x_3 & 0 & -x_1 \\ x_4 & x_2 & x_1 & 0 \end{bmatrix}$$

$D\psi := \Gamma^k \partial_k \psi$
 $A\psi := \Gamma^k A_k \psi$

$$D\psi_\alpha(x) = \sum_{n,\beta} \Gamma^{\alpha\beta n} \partial_{x_n} \psi_\beta(x)$$

$$A_\alpha \psi_\alpha(x) = \sum_{n,\beta} \Gamma^{\alpha\beta n} A_n(x) \psi_\beta(x)$$

$$D = \Gamma^k \partial_k = \begin{bmatrix} 0 & -\partial_4 & \partial_5 & -\partial_6 \\ \partial_4 & 0 & -\partial_3 & -\partial_2 \\ -\partial_5 & \partial_3 & 0 & -\partial_1 \\ \partial_6 & \partial_2 & \partial_1 & 0 \end{bmatrix}$$

$$(\Gamma^k \partial)(\Gamma^l \partial) = -\square^k I_4$$

$$\square = \frac{\partial^2}{\partial x_1 \partial x_6} + \frac{\partial^2}{\partial x_2 \partial x_5} + \frac{\partial^2}{\partial x_3 \partial x_4}$$

・ $D\psi(x) \rightarrow (T_u D\psi)(x) = t_U^{-1} \cdot D\psi(x; \tilde{u})$

・ $A\psi(x) \rightarrow (T_u A\psi)(x) = t_U^{-1} \cdot A\psi(x; \tilde{u})$

終極的な作用素である:

・ $\psi(x) \rightarrow D\psi(x)$

・ $\{ \psi(x), A(x) \} \rightarrow A\psi(x), (D+A)\psi(x)$

ψ Γ_u ψ Γ_u

誘導表現

$\rho: \text{MAN} \rightarrow \text{GL}(V)$ 表現

$P \stackrel{=}{{}^{\text{triv}}}$ ρ triv

$\rho = \rho_{\text{IM}}: M \rightarrow \text{GL}(V)$ Lorentz表現

$\text{SO}(3,3)$

$\Gamma(\text{MAN}, G^*V) \cong \Gamma(\mathbb{R}^6, V)$

$g \in G$

- 1) g : trivial スカラ-場
- 2) g : ベクトル表現 ベクトル場
- 3) g : スピン表現 スピノル場

$$(T_g \rho)(\alpha) = \rho(\alpha, g) \delta(\alpha, g)^{-3+\lambda}$$

$$(T_g A)(\alpha) = \tilde{U}A(\alpha, g) \delta(\alpha, g)^{-3+\lambda}$$

$$(T_g \phi)(\alpha) = U\phi(\alpha, g) \delta(\alpha, g)^{-3+\lambda}$$

$$-\frac{p}{2} + \lambda \stackrel{p=6}{=} -3 + \lambda$$

* $g = g_{\text{triv}} \in \text{SO}(3,3)$ $\delta(\alpha, g) = 1$

* $g = g_{\text{triv}}$: 相似変換 $\delta(\alpha, g) = \tau^{-1}$

* $g = g_{\sigma}$: 反転 $\tau' = \sigma(\alpha) \in \mathbb{R}^6, \tau'_k = \frac{\tau_k}{Q(\alpha)}$

$X' = \sigma(X) \in A(4), \sigma(X) = X^{-1}$

$\delta(\alpha, g) = (\det X)^{\frac{1}{2}} = Q(\alpha)$

- $(T_g D\phi)(\alpha) = \tau \left\{ \frac{\partial}{\partial x_i} (U(\alpha, g)) \right\}^{-1} D\phi(\alpha, g) \delta(\alpha, g)^{-4+\lambda}$
- $(T_g A\phi)(\alpha) = \tau \left\{ \frac{\partial}{\partial x_i} (U(\alpha, g)) \right\}^{-1} A\phi(\alpha, g) \delta(\alpha, g)^{-4+\lambda}$

相似作用素である:

• $\phi(\alpha) \xrightarrow{\quad} D\phi(\alpha)$

$\cup \quad \cup$
 $T_g \quad T_g$

• $\{\phi(\alpha), A(\alpha)\} \xrightarrow{\quad} A\phi(\alpha), D+A\phi(\alpha)$

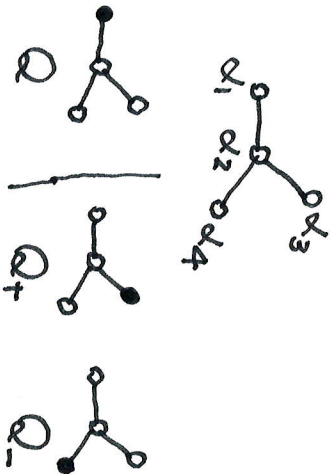
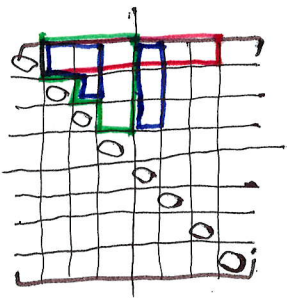
$\cup \quad \cup$
 $T_g \quad T_g$

$$* \quad dx' = \frac{\partial(x', g)}{\partial(x, g)} dx$$

$$\left(\begin{array}{c} \frac{\partial(x', g)}{\partial(x, g)} = U(\alpha, g) \cdot \delta(\alpha, g)^{-1} \\ \frac{\partial(x', g)}{\partial(x, g)} = \frac{\partial(x', g)}{\partial(x, g)} \cdot \frac{\partial(x, g)}{\partial(x, g)} \\ \text{SO}(3,3) \end{array} \right) \left(\begin{array}{c} \delta(\alpha, g) = \det \left(\frac{\partial(x', g)}{\partial(x, g)} \right)^{-\frac{1}{2}} \\ \det \left(\frac{\partial(x', g)}{\partial(x, g)} \right) = \delta(\alpha, g)^{-6} \end{array} \right)$$

Radon 变换 R

\mathbb{Q}^6 ; \mathbb{Q}_+^6 , \mathbb{Q}_-^6
 \mathbb{P}/G \mathbb{P}_+/G \mathbb{P}_-/G
 \checkmark \checkmark \checkmark $(3,3)$ 型計量

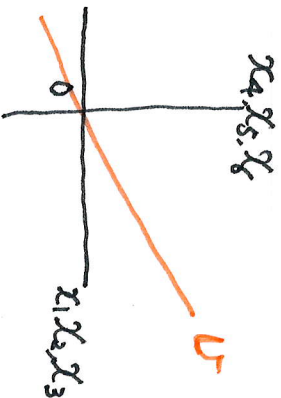


$\tau_{13} : \mathbb{Q} \rightarrow \mathbb{Q}_+$
 $\tau_{14} : \mathbb{Q} \rightarrow \mathbb{Q}_-$
 $\tau_{34} : \mathbb{Q}_+ \rightarrow \mathbb{Q}_-$
 \checkmark \checkmark \checkmark differs.

$x = (x_1, x_2, x_3, x_4, x_5, x_6) \in \mathbb{Q}$
 $U = (U_1, U_2, U_3, U_4, U_5, U_6) \in \mathbb{Q}_\pm$

$\sigma_{\alpha_i} = \alpha_{\sigma(i)}$
 $\sigma_{ij} P_i = P_j$
 $\tau_{ij} \mathbb{P}_\pm = \mathbb{P}_j$
 generic $X_{1,3}$ -平面

$$\begin{cases} x_4 = U_2 x_1 + U_1 x_2 + U_4 \\ x_5 = U_3 x_1 - U_1 x_3 - U_5 \\ x_6 = -U_3 x_2 - U_2 x_3 + U_6 \end{cases}$$
 $dx_1 dx_2 + dx_3 dx_4 + dx_5 dx_6 = 0$



$\mathcal{G}(x) \in \checkmark$ \checkmark \checkmark $(R\mathcal{G})(U) = \int_U \mathcal{G}(x_1, x_2, x_3, x_4, x_5, x_6) dx_1 dx_2 dx_3$

$R : \mathcal{F}_{-3+\lambda}(\mathbb{Q}) \rightarrow \mathcal{F}_{-1+\lambda}(\mathbb{Q}_\pm) \cong \mathcal{F}_{-1+\lambda}(\mathbb{Q})$

図式

自由場

- スカラー場
(ベクトル場も同様)

$$\begin{array}{ccc}
 \mathcal{H}_{\lambda=1}^{\mu=2} & \xrightarrow{\square} & \mathcal{H}_{\lambda=1}^{\mu=4} \\
 \cup & \searrow \text{R} & \cup \\
 \text{Ker } \square \cong \mathcal{H}_{\mu=2}(\mathbb{Q}_+)^{\oplus} \mathcal{H}_{\mu=2}(\mathbb{Q}_-) & & \text{Im } \square \cong \mathcal{H}_{\mu=4}(\mathbb{Q}_+)^{\oplus} \mathcal{H}_{\mu=4}(\mathbb{Q}_-)
 \end{array}$$

- スピノール場

$$\begin{array}{ccc}
 \mathcal{H}_{\lambda=\frac{1}{2}}^{\mu=\frac{5}{2}} & \xrightarrow{\text{D}} & \mathcal{H}_{\lambda=\frac{1}{2}}^{\mu=\frac{7}{2}} \\
 \cup & \searrow \text{R} & \cup \\
 \text{Ker } \text{D} \cong \mathcal{H}_{\mu=\frac{5}{2}}(\mathbb{Q}_+)^{\oplus} \mathcal{H}_{\mu=\frac{5}{2}}(\mathbb{Q}_-) & & \text{Im } \text{D} \cong \mathcal{H}_{\mu=\frac{7}{2}}(\mathbb{Q}_+)^{\oplus} \mathcal{H}_{\mu=\frac{7}{2}}(\mathbb{Q}_-)
 \end{array}$$

相互作用

- $$I = \int_{\mathbb{R}^d} \left(\overline{\psi(x)}^\dagger D \psi(x) + \kappa \overline{\psi(x)}^\dagger A' \psi(x) - \frac{1}{2} (\theta A)^2 \right) dx$$

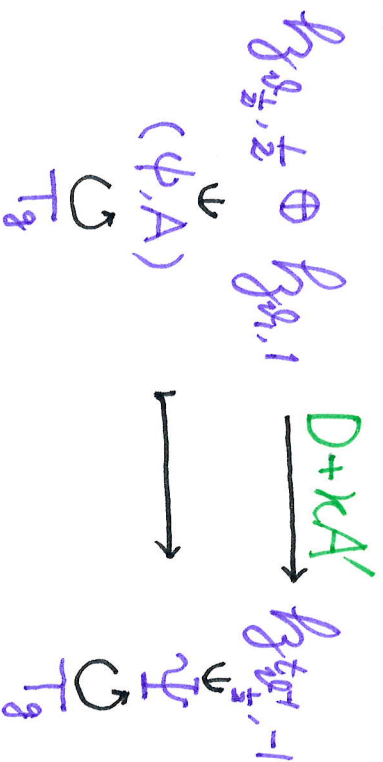
$\overline{\psi}^\dagger$ $\overline{\psi}^\dagger A'$ $\overline{\psi}^\dagger$
 ψ ψ ψ

SO(4,4) 不変 $\Leftrightarrow \lambda = \frac{1}{2}$ (S(2,2) \times S^1)

運動方程式

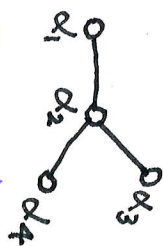
$$\begin{cases} (D + \kappa A') \psi = 0 \\ \square A = \kappa \overline{\psi} \psi \end{cases}$$

- $(D + \kappa A') \psi = \Psi$



◎光, 電子, 陽電子の3対性

○ $Q; Q_+, Q_-$



Q の点 x

$\{\pi_+ \in Q_+ \mid x \text{ を通る } \times \text{ 3 平面 } \pi_+\}$

Q_+ の \times 3 平面

Q_- の \times 3 平面

$\{\pi_- \in Q_- \mid x \text{ を通る } \times \text{ 3 平面 } \pi_-\}$

$\{\pi_+ \in Q_+ \mid \pi_+ \cap \pi_- \text{ は } Q \text{ の } \times \text{ 2 平面}\}$

$\{\pi_- \in Q_- \mid \pi_- \cap \pi_+ \text{ は } Q \text{ の } \times \text{ 2 平面}\}$

Q_- の点 π_-

Q_+ の点 π_+

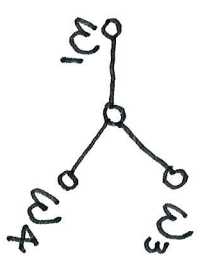
Q の \times 3 平面

幾何的

$Q^6 \subset P^7 = P(V), V^8 = W \oplus W'$

$Q(4,4)$

$Spin(4,4)$ の標準表現 ω_1



$$S^+ = \bigwedge^{even} W = \bigwedge^0 W \oplus \bigwedge^2 W \oplus \bigwedge^4 W \oplus \bigwedge^6 W$$

1 6 1 1

$$S^- = \bigwedge^{odd} W = \bigwedge^1 W \oplus \bigwedge^3 W \oplus \bigwedge^5 W \oplus \bigwedge^7 W$$

4 4 6 4

$(\Lambda^k W \cong \mathbb{R}$ の 2 次形式 $\langle \cdot, \cdot \rangle_{U, S, t}$)

$$Q^+ \subset P(S^+)$$

$$Q^- \subset P(S^-)$$

$$S^+ \times S^- \xrightarrow{s, t} V$$

$\langle U, S, t \rangle_U = \langle U, S, t \rangle_{S^-}$

$Q^+ \cap \omega_1 = S \in S^+ \rightarrow \{U \in V \mid U \cdot S = 0\}$: V の ω_1 4-平面 - Q^+ の ω_1 3-平面

$Q^- \cap \omega_1 = t \in S^- \rightarrow \{U \in V \mid U \cdot t = 0\}$: V の ω_1 4-平面 - Q^- の ω_1 3-平面

$$V \times S^+ \rightarrow S^-, V \times S^- \rightarrow S^+$$

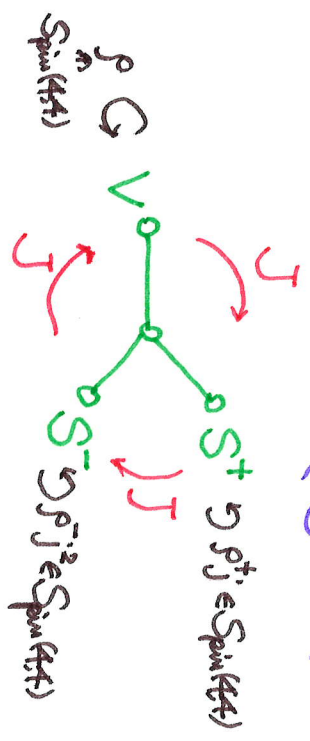
Bilinear

代数的

$A := V \oplus S^+ \oplus S^- \quad (U, S, t) \mapsto \langle U, S, t \rangle_{S^-}$ 3 次形式

J : order 3

$$\begin{cases} V \rightarrow S^+ \\ S^+ \rightarrow S^- \\ S^- \rightarrow V \end{cases}$$



$U \in V$ st. $\langle U, U \rangle_U = 1$

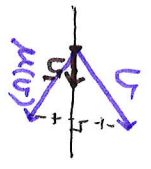
$S_1 \in S^+$ st. $\langle S_1, S_1 \rangle_{S^+} = 1$

$\mu: S^+ \leftrightarrow S^-, V \times V$
 $\mu^2 = id$

$\nu: V \leftrightarrow S^-, S^+ \times V$
 $\nu^2 = id$

$\mu(S) = U \cdot S \quad (S \in S^+)$
 $\mu(U) = 2 \langle U, U \rangle_U U - U \quad (U \in V)$

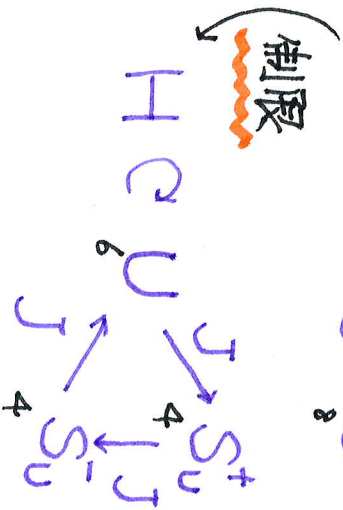
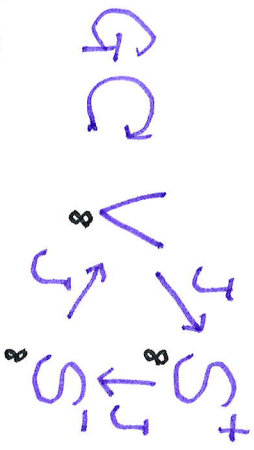
$\nu(S) = 2 \langle S, S_1 \rangle_{S^+} S_1 - S \quad (S \in S^+)$
 $\nu(U) = U \cdot S_1 \quad (U \in V)$



$J := \mu \circ \nu: V \rightarrow S^- \rightarrow S^+$

○ $G = Spin(4,4)$

$U = Spin(3,3) = SL(4)$



→

$V^8 = \langle e_0, e_1, e_2, e_3 | e_4, e_5, e_6, e_7 \rangle$

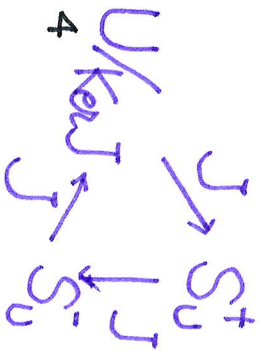
$U = e_0, e_7 : \text{fix}$

$U^6 = \langle e_1, e_2, e_3 | e_4, e_5, e_6 \rangle$

$\hookrightarrow Spin(3,3)$

$S_{U^+} = N_{\text{even}} W_U = N_1^0 \oplus N_3^2$

$S_{U^-} = N_{\text{odd}} W_U = N_1^1 \oplus N_3^3$ (4次元 $\hookrightarrow SL(4,4)$)



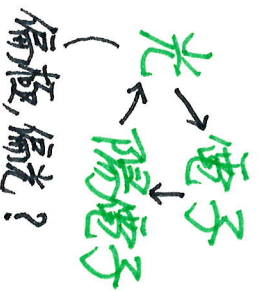
(誘導表現)

* $\Gamma(Q, \square)$ (固定 $U(3)$)

* $\Gamma(O, \square)$

Q, Q, Q 固定

以上, 977 の同値



◎ 伝播関数, Feynman 積分の超関数, 発散積分の正規化

ツインスター積分表示, 留数

○ S 行列
Dyson
相互作用の粒子の散乱
初期の状態と終りの状態の散乱行列 ~ 遷移確率

$$S = U(+\infty, -\infty) = T \exp(i \int_{\mathbb{R}^4} d^4x \mathcal{L}_I(x)) = 1 + \sum_{n \geq 1} \frac{i^n}{n!} \int_{\mathbb{R}^4} d^4x_1 \dots \int_{\mathbb{R}^4} d^4x_n S_n(x_1, \dots, x_n)$$

断熱因子 $e^{-\epsilon|t|}$

時間順序積

擾動展開

$$S_n(x_1, \dots, x_n) = i^n T(\mathcal{L}_I(x_1) \dots \mathcal{L}_I(x_n))$$

正規順序積

QED 

$$S_1(x) = i \delta_I(x) = i e : \Psi(x) \hat{A}(x) \Psi(x) : \quad J^m(x) = \Psi(x) \gamma^m \Psi(x)$$

電流場

$$S_2(x, y) = i^2 T(\mathcal{L}_I(x) \mathcal{L}_I(y)) = -e^2 \sum_n T(: J^m(x) A_m(x) : : J^n(y) A_n(y) :)$$

Compton 散乱 

自己エネルギー 

真空偏極 

* $\langle \beta | S | \alpha \rangle$
* $\langle 0 | S | 0 \rangle$

* Feynman 図 — 内線, 頂点, 外線

Feynman 積分

— 時空 運動量, パラメータ積分 構造関係?

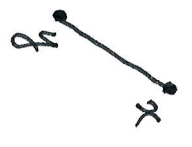
(Feynman, 因果的)

伝播関数

Green関数, フォンディ

以下, 場の演算子 (生成消滅)

1) スカラー場 $\phi(x)$



$$\phi(x)\phi(y) = \langle 0 | T \phi(x)\phi(y) | 0 \rangle = \frac{\Delta^F(x-y)}{(2\pi)^4} = \int_{\mathbb{R}^4} d^4p \frac{e^{ip(x-y)}}{m^2 - p^2 - i0}$$

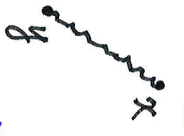
2点関数 真空期待値

massless case, Δ^F

運動量積分表示 (Fourier変換)

$$(\square + m^2)\Delta^F(x-y) = -i\delta(x-y)$$

2) 電磁場 $A_\mu(x)$

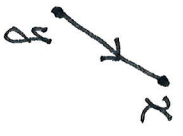


$$A_\mu(x)A_\nu(y) = \langle 0 | T A_\mu(x)A_\nu(y) | 0 \rangle = i g^{\mu\nu} D_0^F(x-y)$$

$$\square D_0^F(x-y) = -\delta(x-y)$$

$$D_0^F(x-y) = -\frac{1}{2\pi^4} \int_{\mathbb{R}^4} d^4p \frac{e^{-ip(x-y)}}{p^2 + i0}$$

3) 電子場 $\psi(x)$



$$\psi_\alpha(x)\bar{\psi}_\beta(y) = \langle 0 | T \psi_\alpha(x)\bar{\psi}_\beta(y) | 0 \rangle = -i S_{\alpha\beta}^F(x-y)$$

$$(i\hat{\partial} + m)_{\alpha\beta} \Delta^F(x-y) = S_{\alpha\beta}^F(x-y)$$

$$(i\hat{\partial} - m) S_{\alpha\beta}^F(x-y) = -\delta_{\alpha\beta}$$

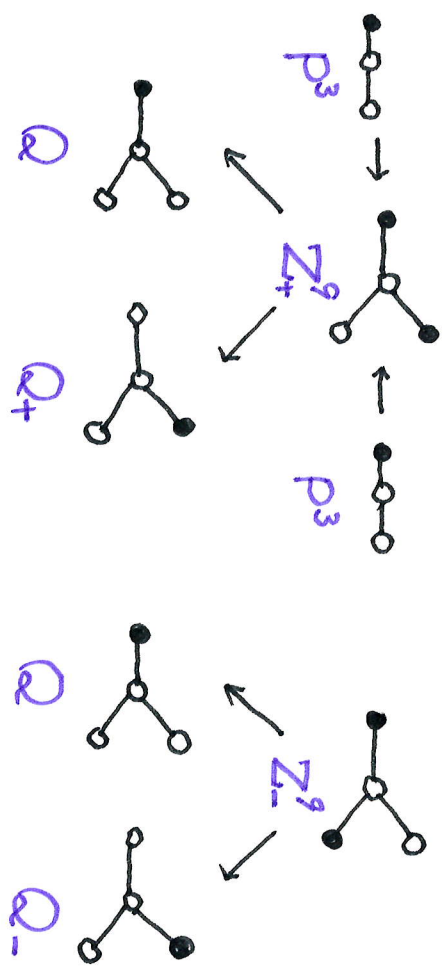
$$S_{\alpha\beta}^F(x-y) = \frac{1}{(2\pi)^4} \int_{\mathbb{R}^4} d^4p \frac{(m - \hat{p})_{\alpha\beta}}{m^2 - p^2 - i0} e^{-ip(x-y)}$$

基本解 (伝播関数) のツイスター-積分表示

A-M (1999) (m,n)型, (m,n-1)型

4	(2,2)	—	1次元	$\subset 3$
6	(3,3)	—	3	$\subset 6$
8	(4,4)	—	6	$\subset 10$
10	(5,5)	—	10	$\subset 15$
12	(6,6)	—	15	$\subset 21$
⋮				

積分 次元 $\mathbb{Q}_+, \mathbb{Q}_-$



(p,2)型の時, Poisson 積分表示
(p,p)型の時, Radon " "

$$\Delta_0^F = \frac{(x_1 x_6 + x_2 x_5 + x_3 x_4)^2}{g} \rightsquigarrow \square \Delta_0^F = 0$$

$$S_0^F = D \Delta_0^F = \frac{-2}{\Gamma/g} \begin{pmatrix} 0 & -x_1 & x_2 & -x_3 \\ x_1 & 0 & -x_4 & -x_5 \\ -x_2 & x_4 & 0 & -x_6 \\ x_3 & x_5 & x_6 & 0 \end{pmatrix} \rightsquigarrow D S_0^F = 0$$

電磁場は, D_0^F

res $\Delta_0^F \dots S_1(g)$
 $\text{res} \int_{g=0} g(x-y)^2 \varphi(y) dy = \varphi(x)$
 $\square \text{res} \Delta_0^F(x-y) = S(y)$

$$\Gamma = \begin{pmatrix} 0 & -x_1 & x_2 & -x_3 \\ -x_1 & 0 & -x_4 & -x_5 \\ x_2 & x_4 & 0 & -x_6 \\ x_3 & x_5 & x_6 & 0 \end{pmatrix}, \quad D = \Gamma/g = \begin{pmatrix} 0 & -x_1 & x_2 & -x_3 \\ x_1 & 0 & -x_4 & -x_5 \\ -x_2 & x_4 & 0 & -x_6 \\ x_3 & x_5 & x_6 & 0 \end{pmatrix}$$

$$\Gamma' = \begin{pmatrix} x_6 & -x_5 & -x_4 & 0 \\ -x_5 & x_4 & -x_3 & -x_2 \\ -x_4 & -x_3 & -x_2 & -x_1 \\ -x_3 & -x_2 & -x_1 & 0 \end{pmatrix}, \quad D = \Gamma'/g = \begin{pmatrix} x_6 & -x_5 & -x_4 & 0 \\ -x_5 & x_4 & -x_3 & -x_2 \\ -x_4 & -x_3 & -x_2 & -x_1 \\ -x_3 & -x_2 & -x_1 & 0 \end{pmatrix}$$

$$D D = \square I_4$$

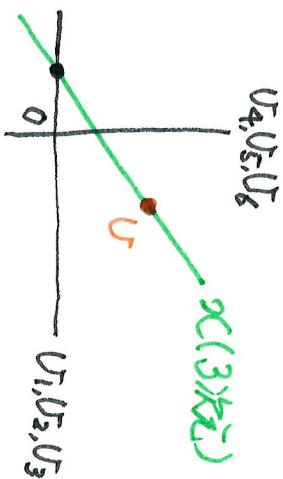
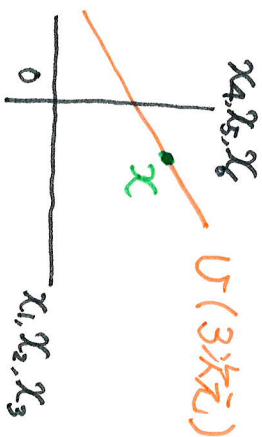
generic

$$\begin{cases} x_4 = U_2 x_1 + U_1 x_2 + U_4 \\ x_5 = U_3 x_1 - U_1 x_3 - U_5 \\ x_6 = -U_3 x_2 - U_2 x_3 + U_6 \end{cases}$$

$$dx_1 dx_6 + dx_2 dx_3 + dx_3 dx_4 = 0$$

$$\begin{cases} U_4 = -x_2 U_1 - x_1 U_2 + x_4 \\ U_5 = -x_3 U_1 + x_1 U_3 - x_5 \\ U_6 = x_3 U_2 + x_2 U_3 + x_6 \end{cases}$$

$$dU_1 dU_6 + dU_2 dU_5 + dU_3 dU_4 = 0$$



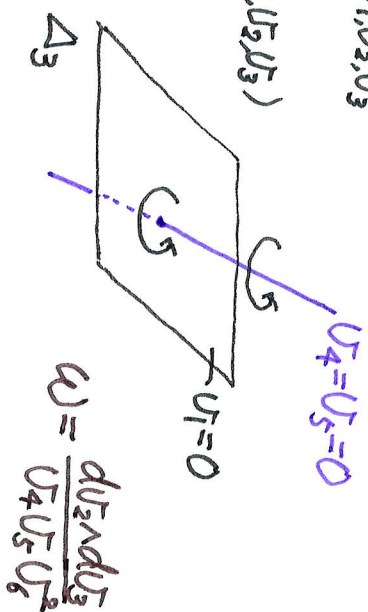
$$\omega := \frac{dU_1 \wedge dU_2}{U_4^2 U_5 U_6} + \frac{dU_1 \wedge dU_3}{U_4 U_5^2 U_6} + \frac{dU_2 \wedge dU_3}{U_4 U_5 U_6^2}$$

$$d\omega = 0 \quad \text{on } x \cong \mathbb{R}^3 \subset \mathbb{C}^3$$

$$[\omega] \in H^2(x - \bigcup_{i=1}^6 \{U_i = 0\}, \mathbb{C})$$

$$\omega \sim \alpha \left(d \log U_2 \wedge d \log U_3 - d \log U_1 \wedge d \log U_3 + d \log U_1 \wedge d \log U_5 \right)$$

$$\frac{1}{(2\pi i)^2} \int_{\Delta} \omega = (x_1 x_2 + x_2 x_3 + x_3 x_4)^{-2} \quad \text{residue}$$



$$\omega = \frac{dU_2 \wedge dU_3}{U_4 U_5 U_6^2}$$

$$\partial_i \int_{\Delta} \omega = \int_{\Delta} \partial_i \omega$$

$$\begin{aligned} \partial_1 \omega, \partial_2 \omega, \partial_3 \omega \\ \partial_4 \omega, \partial_5 \omega, \partial_6 \omega \end{aligned}$$

$$\Delta_0^F(x-y) \Delta_0^F(y-z)$$

$$= \int_{\mathbb{R}^3 \times \mathbb{R}^3} \omega(x-y) \wedge \omega_2(y-z)$$

$$= \int_{\mathbb{R}^3} \omega_1(x-y) \int_{\mathbb{R}^3} \omega_2(y-z)$$

