

毛-又理論入門 第7回

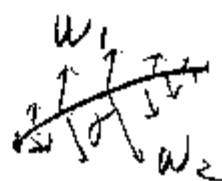
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§13

$M$ : connected Riemannian manifold,  $p, q \in M$   
 $\Omega = \Omega(M; p, q)$  the set of conti. piecewise smooth paths from  $p$  to  $q$   $\omega: [0, 1] \rightarrow M$   
 $\omega \in \Omega$ ,  $T\omega \subset T\Omega$  the set of conti. piecewise smooth vector fields along  $\omega$   
 Let  $\gamma \in \Omega$  geodesic i.e.  $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$  (the velocity vectors are parallel)  
 Then  $\gamma$  is a critical point of the Energy functional  
 $E: \Omega \rightarrow \mathbb{R}$ ,  $E(\omega) = \int_0^1 \|\dot{\omega}\|^2 dt$

Consider the Hessian of  $E$  at  $\gamma$ :

$$E_{**}: T\Omega \times T\Omega \rightarrow \mathbb{R}$$



To calculate  $E_{**}$ , take  $W_1, W_2 \in T\Omega$  and consider any two parameter variation

$$\bar{\alpha}: U \subset \mathbb{R}^2 \rightarrow \Omega(M; p, q)$$

of  $\gamma$  with  $(0,0)$ ,  $\bar{\alpha}(u_1, u_2, t) = \bar{\alpha}(u_1, u_2)(t)$ ,

$\bar{\alpha}(0,0,t) = \gamma(t)$ ,  $\frac{\partial \bar{\alpha}}{\partial u_1}(0,0,t) = W_1(t)$ ,  $\frac{\partial \bar{\alpha}}{\partial u_2}(0,0,t) = W_2(t)$

Then

$$E_{**}(W_1, W_2) := \frac{\partial^2 E(\bar{\alpha}(u_1, u_2))}{\partial u_1 \partial u_2}(0,0)$$

Theorem 13.1 (Second variation formula)

$$\frac{1}{2} \frac{\partial^2 E(\bar{\alpha}(u_1, u_2))}{\partial u_1 \partial u_2}(0,0) = - \int_0^1 \langle W_2(t), \Delta_t \frac{DW_1}{dt} \rangle$$

$$- \int_0^1 \langle W_2(t), \frac{D^2 W_1}{dt^2} + (R(V, W_1)W_1)(t) \rangle dt$$

where  $V = \dot{\gamma}$ ,  $\Delta_t \frac{DW_1}{dt} = \frac{DW_1}{dt}(t^+) - \frac{DW_1}{dt}(t^-)$ ,  $(\frac{DW_1}{dt} = \nabla_{\dot{\gamma}} W_1)$   
 "discontinuity"

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(1) By (12.2),  $\frac{1}{2} \frac{\partial E(\bar{x})}{\partial u_2} = - \sum_t \langle \frac{\partial x}{\partial u_2}, \Delta_t \frac{\partial x}{\partial t} \rangle - \int_0^1 \langle \frac{\partial x}{\partial u_2}, \nabla_{\frac{\partial x}{\partial t}} \frac{\partial x}{\partial t} \rangle dt$

By (8.3),

$\frac{1}{2} \frac{\partial^2 E(\bar{x})}{\partial u_1 \partial u_2} = - \sum_t \langle \nabla_{\frac{\partial x}{\partial u_1}} \frac{\partial x}{\partial u_2}, \Delta_t \frac{\partial x}{\partial t} \rangle - \sum_t \langle \frac{\partial x}{\partial u_2}, \nabla_{\frac{\partial x}{\partial u_1}} (\Delta_t \frac{\partial x}{\partial t}) \rangle dt$   
 $- \int_0^1 \langle \nabla_{\frac{\partial x}{\partial u_1}} \frac{\partial x}{\partial u_2}, \nabla_{\frac{\partial x}{\partial t}} \frac{\partial x}{\partial t} \rangle dt - \int_0^1 \langle \frac{\partial x}{\partial u_2}, \nabla_{\frac{\partial x}{\partial u_1}} (\nabla_{\frac{\partial x}{\partial t}} \frac{\partial x}{\partial t}) \rangle dt$

Set  $(u_1, u_2) = (0, 0)$

$\|_0 (u_1, u_2) = (0, 0) \text{ a.e. } \mathbb{T}$

$\therefore \frac{1}{2} \frac{\partial^2 E(\bar{x})}{\partial u_1 \partial u_2} (0, 0) = - \sum_t \langle \frac{\partial x}{\partial u_2}, \Delta_t (\nabla_{\frac{\partial x}{\partial u_1}} \frac{\partial x}{\partial t}) \rangle dt \quad (13.2)$

$- \int_0^1 \langle \frac{\partial x}{\partial u_2}, \nabla_{\frac{\partial x}{\partial u_1}} (\nabla_{\frac{\partial x}{\partial t}} \frac{\partial x}{\partial t}) \rangle dt$   
 $= - \sum_t \langle \frac{\partial x}{\partial u_2}, \Delta_t (D_j W_1) \rangle dt$

(8.2)

(9.2)

$- \int_0^1 \langle W_2, \nabla_{\frac{\partial x}{\partial t}} (\nabla_{\frac{\partial x}{\partial u_1}} \frac{\partial x}{\partial t}) + R(\dot{x}, W_1) \dot{x} \rangle dt$

$\| \nabla_{\frac{\partial x}{\partial t}} \frac{\partial x}{\partial u_1}$

(13.3)

$= - \sum_t \langle W_2, \Delta_t (D_j W_1) \rangle dt$

$- \int_0^1 \langle W_2, D_j (\nabla_{\dot{x}} W_1) + R(\dot{x}, W_1) \dot{x} \rangle dt //$

Cor. 13.4  $E_{**}(W_1, W_2) = \frac{\delta^2 E(\bar{x})}{\partial u_1 \partial u_2} (0, 0)$  is well defined symmetric bilinear function.

(1) Th. 13.1 //

Remark 13.5

$$E_{**}(W, W) = \frac{d^2 E(\bar{\alpha})}{du^2}(0) \quad \text{for}$$

$$\bar{\alpha}: (-\epsilon, \epsilon) \rightarrow \Omega, \quad \frac{d\bar{\alpha}}{du}(0) = W$$

↑ 1-param. variation

$$\textcircled{1} \quad \beta(u_1, u_2, t) := \alpha(u_1 + u_2, t)$$
$$\frac{\partial^2 E(\beta)}{\partial u_1 \partial u_2} \Big|_{(u_1, u_2) = (0, 0)} = \frac{\partial^2 E(\bar{\alpha})}{\partial u^2} \Big|_{u=0}$$

最短測地線

Lemma 13.6.  $\gamma \in \Omega(M; p, q)$  : minimal geodesic

$\Rightarrow E_{**}$  positive semi-definite

$$\text{index}_\gamma E_{**} = 0$$

$$\textcircled{1} \quad E(\bar{\alpha}(u)) \geq E(\gamma) = E(\bar{\alpha}(0)).$$

↑  $\gamma$  minimal

$$\therefore \frac{d^2 E(\bar{\alpha})}{du^2}(0) \geq 0 \quad \therefore E_{**}(W, W) \geq 0$$

$$\forall W \in T_p \Omega, \forall \bar{\alpha}$$

//

Example  $p=q$ ,  $\gamma$  : constant geodesic

$\Rightarrow \gamma$  : minimal geodesic

Then  $\text{index}_\gamma E_{**} = 0$

§14

$M$ : Riemannian manifold  $\dim M = n$

$\gamma: [a, b] \rightarrow M$  geodesic ( $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$ )

$J: [a, b] \rightarrow TM$  vector field along  $\gamma$ ,  $J(t) \in T_{\gamma(t)} M$

Definition:

$J$ : Jacobi field (ヤコビ場) of  $\gamma$

$\Leftrightarrow \nabla_{\dot{\gamma}}^2 J + R(\dot{\gamma}, J)\dot{\gamma} = 0$  (\*) Jacobi equation  
↑ curvature tensor

$P_1, \dots, P_n$  orthonormal parallel field along  $\gamma$ .

Let  $J(t) = \sum_{i=1}^n f^i(t) P_i(t)$

$\nabla_{\dot{\gamma}} J = \sum_i \left( \frac{df^i}{dt} P_i + f^i \nabla_{\dot{\gamma}} P_i \right)$  ) (  $\nabla_{\dot{\gamma}}$  は  $\gamma$  に沿って  $\frac{d}{dt}$  で共変微分すること )

$\nabla_{\dot{\gamma}}^2 J = \sum_i \nabla_{\dot{\gamma}} \left( \frac{df^i}{dt} P_i \right)$   
 $= \sum_i \frac{d^2 f^i}{dt^2} P_i + \frac{df^i}{dt} \nabla_{\dot{\gamma}} P_i$

$R(\dot{\gamma}, J)\dot{\gamma} = \sum_{j=1}^n f^j R(\dot{\gamma}, P_j)\dot{\gamma}$

(\*)  $\Leftrightarrow \sum_{i=1}^n \frac{d^2 f^i}{dt^2} P_i + \sum_{j=1}^n f^j R(\dot{\gamma}, P_j)\dot{\gamma} = 0$

$\Leftrightarrow \forall k \quad \left\langle \sum_{i=1}^n \frac{d^2 f^i}{dt^2} P_i + \sum_{j=1}^n f^j R(\dot{\gamma}, P_j)\dot{\gamma}, P_k \right\rangle = 0$

$\Leftrightarrow \forall k \quad \frac{d^2 f^k}{dt^2} + \sum_{j=1}^n f^j \underbrace{\langle R(\dot{\gamma}, P_j)\dot{\gamma}, P_k \rangle}_{a_j^k} = 0$

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$$(*) \Leftrightarrow \frac{d^2 f^k}{dt^2} + \sum_{j=1}^n a_j^k(t) f^j(t) = 0 \quad (1 \leq k \leq n)$$

2nd order ODE

$J$  is determined by  $J(a)$ ,  $\nabla_{\dot{\gamma}} J(a) \in T_{\gamma(a)} M$

initial data

i.e.  $f^1(a), \dots, f^n(a), \frac{df^1}{dt}(a), \dots, \frac{df^n}{dt}(a)$ .

初期値問題  $\neq$  境界値問題を考へる

Definition:  $p, q \in M$   $\gamma: [a, b] \rightarrow M$  geodesic

$\gamma(a) = p, \gamma(b) = q$ , possibly  $p = q$   $a \neq b$

$p$  and  $q$  are conjugate along  $\gamma$  (共役点)

$\stackrel{\text{def}}{\Leftrightarrow} \exists$  Jacobi field of  $\gamma$  with  $J(a) = 0, J(b) = 0$ .

multiplicity of  $\gamma$  for  $p$  &  $q$

2n個の条件

$$:= \dim \{ J: \text{Jacobi field of } \gamma \mid J(a) = 0, J(b) = 0 \}$$

$p, q$  conjugate  $\Leftrightarrow$  multiplicity  $> 0$

$\gamma \in \Omega = \Omega(M; p, q)$  geodesic  $J: [0, 1] \rightarrow M$

$\text{Ex}^*: T_p \Omega \times T_p \Omega \rightarrow \mathbb{R}$  Hessian

$N := \{ W_1 \in T_p \Omega \mid \text{Ex}^*(W_1, W_2) = 0 \text{ for } \forall W_2 \in T_p \Omega \}$

linear subspace of  $T_p \Omega$

$\nu := \dim_{\mathbb{R}} N$  nullity of  $\gamma$  (退化次数)

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Theorem 14.1

$N = \{J : \text{Jacobi field of } \gamma \mid J(0)=0, J(1)=0\}$

$\exists \neq \text{ degenerate} \iff \delta(0)=p, \delta(1)=q$  are conjugate points along  $\gamma$

Ⓛ nullity of  $\gamma = \text{multiplicity of } p \& q \text{ along } \gamma$

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Ⓛ  $\gamma$  smooth, Th 13.1

C Suppose  $W_i \in N$  and  $W_i$  is smooth on subintervals of  $0 = t_0 < t_1 < \dots < t_k = 1$ .

Using Th 13.1, we have  $W_i|_{[t_{i-1}, t_i]}$  Jacobi field of  $\gamma|_{[t_{i-1}, t_i]}$ , and  $\nabla_j W_i$  is continuous.

Then by the uniqueness of initial value problem of Jacobi equation, we see  $W_i$  smooth and a Jacobi field of  $\gamma$ . //

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Remark:  $0 \leq \nu < n$

Ⓛ By the condition  $J(0)=0$ , we have  $\nu \leq n$ .

$\exists$  Jacobi field  $J_{\gamma(t)}$  s.t.  $J(0)=0, J(1) \neq 0$ . //

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Example 1.  $M$  flat ( $\iff R(X, Y)Z = 0$  for  $\forall X, Y, Z$ )  
Then Jacobi equation  $\frac{d^2 f^i}{dt^2} = 0$   $f^i$ : linear  
 $\forall \gamma$  geodesic  $\nexists$  conj. pts,  $\exists \neq$ : non-degenerate.

Lemma 14.3  $\bar{\alpha}: (-\epsilon, \epsilon) \rightarrow \Omega$  variation of a geodesic  $\gamma$  by geodesics

$\Rightarrow W(t) := \frac{\partial \alpha}{\partial u}(0, t)$  is a Jacobi field of  $\gamma$

(1)  $\alpha(u, t) := \bar{\alpha}(u)(t)$

$\nabla_{\frac{\partial \alpha}{\partial t}} \frac{\partial \alpha}{\partial t} = 0$

$0 = \nabla_{\frac{\partial \alpha}{\partial u}} \left( \nabla_{\frac{\partial \alpha}{\partial t}} \frac{\partial \alpha}{\partial t} \right) = \nabla_{\frac{\partial \alpha}{\partial t}} \left( \nabla_{\frac{\partial \alpha}{\partial u}} \frac{\partial \alpha}{\partial t} \right) + R \left( \frac{\partial \alpha}{\partial t}, \frac{\partial \alpha}{\partial u} \right) \frac{\partial \alpha}{\partial t}$   
 (9.2)

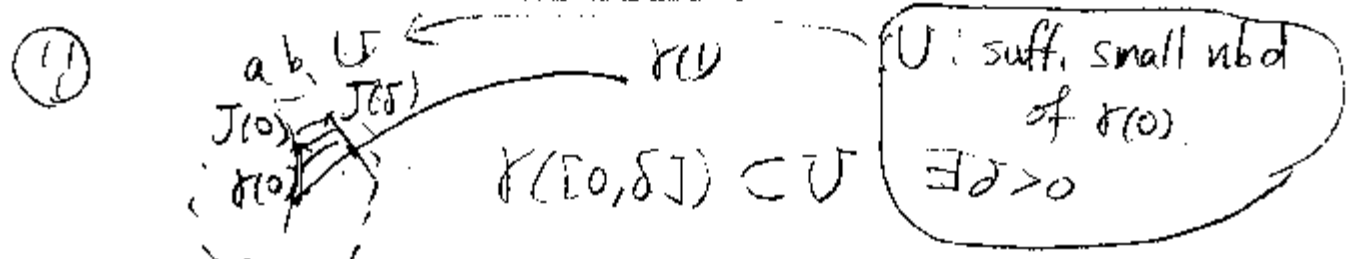
$\stackrel{(8.7)}{=} \nabla_{\frac{\partial \alpha}{\partial t}} \left( \nabla_{\frac{\partial \alpha}{\partial t}} \frac{\partial \alpha}{\partial u} \right) + R \left( \frac{\partial \alpha}{\partial t}, \frac{\partial \alpha}{\partial u} \right) \frac{\partial \alpha}{\partial t}$

$\therefore \frac{\partial \alpha}{\partial u} \Big|_{u=u_0}$  satisfies Jacobi equation of  $\alpha \Big|_{u=u_0}$

$u_0 = 0 \quad \frac{\partial \alpha}{\partial u} \Big|_{u=0}$  is a Jacobi field of  $\gamma$ . //

Lemma 14.4  $\forall$  Jacobi field  $J$  of  $\gamma$  is obtained by a variation of  $\gamma$  by geodesics.

( $\exists \alpha: (-\epsilon, \epsilon) \times [0, 1] \rightarrow M, \alpha \Big|_{u=\text{const}}$  geodesic)



$J(0) \in T_{\gamma(0)} M \quad J(\delta) \in T_{\gamma(\delta)} M$   
 $\forall a, b: (-\epsilon, \epsilon) \rightarrow U, a(0) = \gamma(0), \dot{a}(0) = J(0), b(0) = \gamma(\delta), \dot{b}(0) = J(\delta)$   
 $\alpha: (-\epsilon, \epsilon) \times [0, \delta] \rightarrow M$  s.t.  $\bar{\alpha}(u)$  is the unique geodesic from  $a(u)$  to  $b(u)$ . (minimal)

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$J(\gamma)$  is the space of Jacobi field along  $\gamma$ ,

$$\dim J(\gamma) = 2n.$$

$$\begin{array}{ccc} \overset{(2n)}{J(\gamma)} & \xrightarrow{k} & \overset{(2n)}{J(M[0, \delta])} \xrightarrow{l} \overset{(2n)}{T_{\gamma(0)}M \times T_{\gamma(\delta)}M} \\ J & \longmapsto & J|_{[0, \delta]} \longmapsto (J(0), J(\delta)) \end{array}$$

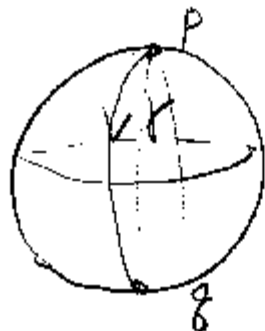
$k, l$  are surjective.

$\therefore k, l$  are isomorphism.

Take  $\varepsilon$  sufficiently small  $\alpha: (-\varepsilon, \varepsilon) \times [0, \delta] \rightarrow M$

extends to a variation  $\alpha: (-\varepsilon, \varepsilon) \times [0, 1] \rightarrow M$   
by geodesics with  $\frac{\partial \alpha}{\partial u}|_{u=0} = J$ .

Example 2.  $M = S^n$ ,  $p, q$  anti-podal points



$p$  and  $q$  are conj. of multiplicity  $n-1$

rotations fixing  $p, q$  gives  $n-1$  independent Jacobi fields.

by Lemma 4.3