

トポロジー理論入門 第5回

5-1

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M : connected Riemannian manifold.

smooth curve $\gamma: I \rightarrow M$ is a geodesic (測地線)

$$\stackrel{\text{def}}{\iff} \nabla_{\dot{\gamma}} \dot{\gamma} = 0 \quad \begin{array}{l} \uparrow \\ \text{interval} \\ \text{(区間)} \end{array} \quad \left(\dot{\gamma} = \frac{d\gamma}{dt} \right)$$

$$\left(\frac{D}{dt} \frac{d\gamma}{dt} \right)$$

① γ geodesic $\Rightarrow \dot{\gamma}$ constant

$$\textcircled{!} \frac{d}{dt} (\|\dot{\gamma}\|^2) = \frac{d}{dt} \langle \dot{\gamma}, \dot{\gamma} \rangle = 2 \langle \nabla_{\dot{\gamma}} \dot{\gamma}, \dot{\gamma} \rangle = 0 \quad //$$

$$s(t) := \int_{t_0}^t \|\dot{\gamma}(t)\| dt + s(t_0) \quad \leftarrow \begin{array}{l} \text{Take } s(t_0) \\ \text{for a fixed } t_0 \in I \end{array}$$

arclength function

If $\|\dot{\gamma}\| = 0$, then s is constant.

$$\text{If } \|\dot{\gamma}\| = c \neq 0 \quad s(t) = c(t - t_0) + s(t_0)$$

$$s = \exists a t + \exists b \quad a, b \in \mathbb{R} \quad a \neq 0,$$

local coord. x^1, \dots, x^n of M

$$\gamma(t) = (x^1(t), \dots, x^n(t))$$

$$\dot{\gamma}(t) = \sum_{i=1}^n (x^i)' \frac{\partial}{\partial x^i}$$

$$\nabla_{\dot{\gamma}} \dot{\gamma} = \sum_i (x^i)'' \frac{\partial}{\partial x^i} + \sum (x^i)' \nabla_{\dot{\gamma}} \frac{\partial}{\partial x^i}$$

$$= \sum_i (x^i)'' \frac{\partial}{\partial x^i} + \sum_j (x^i)' (x^j)' \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}$$

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$$\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i} = \sum_k \Gamma_{ij}^k \frac{\partial}{\partial x^k}$$

$$\therefore \nabla_{\dot{\gamma}} \dot{\gamma} = \sum_k \left(\frac{d^2 x^k}{dt^2} + \sum_{ij} \frac{dx^i}{dt} \cancel{x^j} \Gamma_{ji}^k \right) \frac{\partial}{\partial x^k}$$

$\frac{dx^j}{dt}$
↓
 $\Gamma_{ji}^k(x(t))$
 $\frac{dx^j}{dt}$

$$\gamma : \text{geodesic} \iff \frac{d^2 x^k}{dt^2} + \sum_{ij} \Gamma_{ji}^k \cancel{x^j} \frac{dx^i}{dt} = 0$$

non-linear 2nd order ordinary differential equation

Lemma 10.2. M : Riemannian manifold
 $\forall p_0 \in M, p_0 \in \exists U$ open neighborhood $\exists \epsilon > 0$ such that
 $\forall p \in U, \forall v \in T_p M$ with $\|v\| < \epsilon, \exists \gamma_v : (-2, 2) \rightarrow M$
geodesic satisfying

$$\gamma_v(0) = p, \quad \frac{d\gamma_v}{dt}(0) = v$$

⊙ Exponential map (指數寫像)

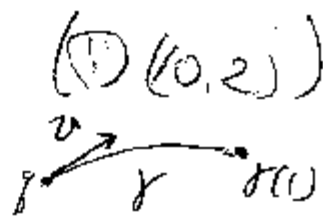
$p \in M, v \in T_p M, \|v\|$ sufficiently small

$\Rightarrow \exists \gamma$ geodesic $\gamma : [0, 1] \rightarrow M$

such that $\gamma(0) = p, \frac{d\gamma}{dt}(0) = v$

$$\exp_p(v) := \gamma(1) \in M$$

$$\exp_p : \{v \in T_p M \mid \|v\| < \epsilon\} \rightarrow M$$



exponential map

Remark: $\gamma(t) = \exp_p(t v)$ holds.

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Definition (M, g) geodesically complete

$\forall p \in M, \forall v \in T_p M, \exp_p(v)$ is defined.

① By the uniqueness of geodesics by initial condition, \forall geodesic $\gamma_0: [a, b] \rightarrow M$ is (uniquely) extended to a geodesic $\gamma: \mathbb{R} \rightarrow M$ if M is geodesically complete.

Tangent bundle:

$$TM = \{ (p, v) \mid p \in M, v \in T_p M \}$$

$(U; u^1, \dots, u^n)$ local coord. of M

$p \in U, T_p M \ni v$

$$v = \sum_{i=1}^n t^i \frac{\partial}{\partial u^i} \Big|_p$$

$(TU = U \times \mathbb{R}^n, u^1, \dots, u^n, t^1, \dots, t^n)$ local coord. of TM

Lemma 10.3 $\forall p \in M, \exists W$ open neighborhood of $p, \exists \epsilon > 0$

(1) $\forall p_1, p_2 \in W$ are connected by $\exists!$ geodesic of length $< \epsilon$.

(2) For geodesic $t \mapsto \exp_{p_1}(tv)$ connecting p_1, p_2 , the initial condition $(p_1, v) \in TM$ depends smoothly on (p_1, p_2)

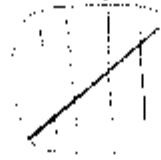
(3) $\forall p \in W, \exp_p: \{ v \in T_p M \mid \|v\| < \epsilon \} \rightarrow \bigcup_{W \subset U} U \subset M$ is a diffeomorphism.

① $\forall p \in M, (p, 0) \in \exists V \subset TM, F: V \rightarrow M \times M$

$$F(p, v) := (p, \exp_p(v)), \quad F(p, 0) = (p, p)$$

inverse map theorem: $(p, 0) \in \exists V' \subset V$,

$$F|_{V'}: V' \rightarrow F(V') \subset M \times M, \quad \exists p \in W \subset M$$



Lemma 10.3

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Theorem 10.4 $p \in M$ $p \in W \subset M$, $\varepsilon > 0$
 $\gamma_0, \gamma_1 \in W$, $\gamma: [0,1] \rightarrow M$ geodesic connecting γ_0, γ_1 in M
 with length $< \varepsilon$, $\omega: [0,1] \rightarrow M$ any piecewise smooth
 path connecting γ_0, γ_1 . Then

$$\int_0^1 \|\dot{\gamma}\| dt \leq \int_0^1 \|\dot{\omega}\| dt.$$

The equality holds if and only if $\omega([0,1]) = \gamma([0,1])$

⊙ A geodesic is a "local minimizer".

Lemma 10.5 In U_g as in Lemma 10.3,
 the geodesic through g intersect orthogonally with
 $\{\exp_g(v) \mid v \in T_g M, \|v\| = \text{const}\}$

⊙ $\forall v: I \rightarrow \{v \in T_g M \mid \|v\|=1\} \subset T_g M$
 curve

We show

$$t \mapsto \exp_g(r_0 v(t)) \quad 0 < r_0 \leq \varepsilon \quad \text{and}$$

$$r \mapsto \exp_g(r v(t_0)) \quad t_0 \in I$$

are intersect orthogonally at $\exp_g(r_0 v(t_0))$.

$$f(r,t) := \exp_g(r v(t))$$

It is sufficient to show $\left\langle \frac{\partial f}{\partial r}, \frac{\partial f}{\partial t} \right\rangle = 0$

$$\frac{\partial}{\partial r} \left\langle \frac{\partial f}{\partial r}, \frac{\partial f}{\partial t} \right\rangle = \left\langle \nabla_{\frac{\partial f}{\partial r}} \frac{\partial f}{\partial r}, \frac{\partial f}{\partial t} \right\rangle + \left\langle \frac{\partial f}{\partial r}, \nabla_{\frac{\partial f}{\partial r}} \frac{\partial f}{\partial t} \right\rangle$$

$$= \left\langle \frac{\partial f}{\partial r}, \nabla_{\frac{\partial f}{\partial r}} \frac{\partial f}{\partial t} \right\rangle = \frac{1}{2} \frac{\partial}{\partial t} \left\langle \frac{\partial f}{\partial r}, \frac{\partial f}{\partial r} \right\rangle = \frac{1}{2} \frac{\partial}{\partial t} \|v\|^2 = 0$$

(Lemma 8.7)

$$\frac{\partial}{\partial t} \left\langle \frac{\partial f}{\partial r}, \frac{\partial f}{\partial t} \right\rangle = 0$$

5.5

Lemma 10.6 $\omega: [a, b] \rightarrow U_g \setminus \{p\}$
 $\omega(t) = \exp_p(r(t)v(t))$ $0 < r(t) < \epsilon$ $\|v(t)\| = 1$

$$\Rightarrow \int_a^b \|\dot{\omega}\| dt \geq |r(b) - r(a)| = \int_a^b \|\dot{r}\| dt$$



(*) $f(r, t) := \exp_p(rv(t))$, $\omega(t) = f(r(t), t)$

$$\dot{\omega} = \frac{\partial f}{\partial r} \dot{r}(t) + \frac{\partial f}{\partial t}$$

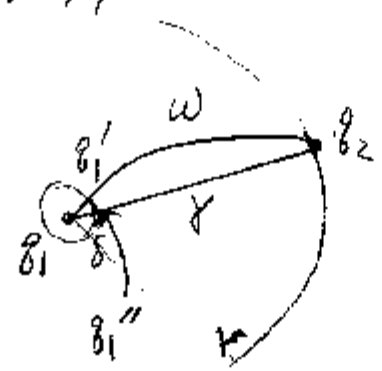
$$\|\dot{\omega}\|^2 = |\dot{r}(t)|^2 + \left\| \frac{\partial f}{\partial t} \right\|^2 \geq |\dot{r}(t)|^2 \quad (\text{Lemma 10.5})$$

$$(\Leftrightarrow \frac{\partial f}{\partial t} = 0 \Leftrightarrow \dot{v} = 0)$$

$$\int_a^b \|\dot{\omega}\| dt \geq \int_a^b |\dot{r}(t)| dt \geq |r(b) - r(a)|$$

$\Leftrightarrow r(t)$ monotone, $v(t)$ constant //

Proof of Th. 10.4



ω の q_1' から q_2 の長さ $\geq \gamma$ の q_1'' から q_2 の長さ

Lemma 10.6
 $= r - \delta$

ω の q_1 から q_2 の長さ $\geq r = \gamma$ の q_1 から q_2 の長さ //

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Definition. A geodesic $\gamma: [a, b] \rightarrow M$ is called a minimal (極小, 最短) geodesic or a minimizer (最短経路)

$\stackrel{\text{def}}{\iff} \forall \omega: [\alpha, \beta] \rightarrow M$ piecewise smooth path

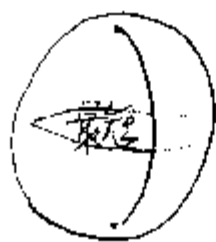
$$\omega(\alpha) = \gamma(a), \quad \omega(\beta) = \gamma(b)$$

$$\implies \int_{\alpha}^{\beta} \|\dot{\omega}\| dt \geq \int_a^b \|\dot{\gamma}\| dt$$

length of ω

length of γ

Remark. 志賀浩二先生は minimal を極小と訳しているが、それ(?)は最小あるいは(長さについてなので)最短と訳するのがよい。



(M, g) connected Riemannian manifold, $p, q \in M$

$$P(p, q) := \inf \left\{ \int_{\alpha}^{\beta} \|\dot{\omega}\| dt \mid \omega: [\alpha, \beta] \rightarrow M \text{ piecewise smooth} \right. \\ \left. \omega(\alpha) = p, \omega(\beta) = q \right\}$$

(M, P) metric space which gives the same topology on M (as a manifold)

Cor. 10.8 (of Th. 10.4) $\forall K \subset M$ compact, $\exists \delta > 0$
 $\forall p, q \in K$ with $P(p, q) \leq \delta$, $\exists 1$ minimal geodesic
 $\gamma: [a, b] \rightarrow M$ $\gamma(a) = p, \gamma(b) = q$.

γ depend smoothly on p, q (see Lemma 10.3)

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Theorem 10.9 (Hopf-Rinow) M : connected Riemannian,
 M : geodesically complete \Rightarrow

$\forall p, q \in M \exists \gamma$ geodesic connecting p and q .

Corollary 10.10. M : geodesically complete

$\Rightarrow \forall X \subseteq M$ bounded subset (for P), \bar{X} (closure) is compact

M : geodesically complete $\Leftrightarrow M$: complete as metric space

① \Rightarrow diameter $(X) = d$, $\forall p \in X \exp_p: T_p M \rightarrow M$

$X \subset \exp_p(\{v \in T_p M \mid \|v\| \leq d\})$ compact

$\therefore \bar{X}$: compact

\forall Cauchy sequence converges, $\therefore M$: complete

$\Leftarrow M$: complete, By Lemma 10.3, M is geod. complete //

Example $M = \mathbb{R}^n$ Euclidean space

geodesics are straight lines. geod. complete

$M = S^n$ geodesics are great circles

$M = \mathbb{R}^2 \setminus \{0\}$



non-complete

