

Total variation for image denoising: Theory and examples in the anisotropic case.

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Preliminaries.

Let n be a positive integer and let Ω be an open subset of \mathbb{R}^n . Given an integer k , a k -current T on Ω is a continuous linear functional

$$T : \mathcal{D}^k(\Omega) \rightarrow \mathbb{R};$$

here $\mathcal{D}^k(\Omega)$ is the vector space of smooth compactly supported differential forms of degree k on Ω . We let

$$\mathcal{D}_k(\Omega)$$

be the vector space of k -currents on Ω . The boundary ∂T is the $(k - 1)$ -current defined by

$$\partial T(\psi) = T(d\psi) \quad \text{for } \psi \in \mathcal{D}^{k-1}(\Omega);$$

here $d : \mathcal{D}^{k-1}(\Omega) \rightarrow \mathcal{D}^k(\Omega)$ is exterior differentiation.

A simple example.

Suppose $P : [a, b] \rightarrow \Omega$ is Lipschitzian. For each smooth compactly supported 1-form ψ on Ω we set

$$T(\psi) = \int_a^b \psi(P(t))(P'(t)) d\mathcal{L}^1 t;$$

so $T \in \mathcal{D}_1(\Omega)$. Note that the same T results if we reparameterize P in an orientation preserving way. Also, by the Fundamental Theorem of Calculus,

$$\partial T(g) = g(P(b)) - g(P(a)) \quad \text{for } g \in \mathcal{D}^0(\Omega).$$

In other words, ∂ is defined so as to make Stokes' Theorem a definition.

Representability by integration.

We say the k -current T is **representable by integration** if there exist a Radon measure μ on Ω and a locally μ summable k -vector field ξ such that

$$T(\psi) = \int \psi(\xi(x)) d\mu x \quad \text{for } \psi \in \mathcal{D}^k(\Omega).$$

This will be the case if and only if

$$\sup\{|T(\psi)| : \psi \in \mathcal{D}^k(\Omega) \text{ and } \|\psi\| \leq f\} < \infty$$

whenever $f : \Omega \rightarrow [0, \infty)$ is continuous and compactly supported.

Representability by integration, continued.

Suppose

$$\Phi : \bigwedge_k \mathbb{R}^n \rightarrow [0, \infty)$$

is continuous and satisfies

$$\Phi(t\xi) = t\Phi(\xi) \quad \text{whenever } t \in [0, \infty) \text{ and } \xi \in \bigwedge_k \mathbb{R}^n;$$

we call such a function Φ a **integrand (of degree k)**; we say Φ is **positive** if $\Phi(\xi) > 0$ for $\xi \in: \bigwedge_k \mathbb{R}^n \sim \{0\}$.

Suppose Φ is a positive integrand and μ, ξ are as above; we set

$$\int_T \Phi = \int \Phi(\xi(x)) d\mu x \in [0, \infty].$$

Owing to the homogeneity of Φ the quantity $\int_T \Phi$ is well defined.

We let

$$\mathbf{M}(T) = \int_T \|\cdot\| \in [0, \infty);$$

here $\|\cdot\|$ is the **comass** on $\bigwedge_k \mathbb{R}^n$. One calls $\mathbf{M}(T)$ the **mass of T** . Note that

$$\begin{aligned} \mathbf{M}(T) < \infty &\Leftrightarrow \int_T \Phi < \infty \quad \text{for any positive integrand } \Phi \\ &\Leftrightarrow \int_T \Phi < \infty \quad \text{for some positive integrand } \Phi. \end{aligned}$$

The current associated to a function.

Suppose $f \in \mathbf{L}_1^{loc}(\Omega)$. We associate an n -dimensional current

$$[f] : \mathcal{D}^n(\Omega) \rightarrow \mathbb{R}$$

by requiring that

$$[f](\phi \mathbf{V}^n) = \int f \phi d\mathcal{L}^n \quad \text{for } \phi \in \mathcal{D}(\Omega).$$

Here

$$\mathbf{V}^n = \mathbf{e}^1 \wedge \cdots \wedge \mathbf{e}^n \in \bigwedge^n \mathbb{R}^n$$

is the standard volume n -form on \mathbb{R}^n .

Bounded variation.

We say f is of **locally bounded variation** and write $f \in \mathbf{BV}^{loc}(\Omega)$ if $\partial[f]$ is representable by integration. We say f is of **bounded variation** and write $f \in \mathbf{BV}(\Omega)$ if $\mathbf{M}([f]) + \mathbf{M}(\partial[T]) < \infty$. Note that this condition is depends on neither the choice of volume form nor the choice of inner product on \mathbb{R}^n .

Some examples.

Suppose $f : \Omega \rightarrow \mathbb{R}$ is Lipschitzian. Then $f \in \mathbf{L}_1^{loc}(\Omega)$ and

$$\mathbf{M}(\partial[f]) = \int_{\Omega} |\nabla f| d\mathcal{L}^n.$$

More generally, for any integrand Φ ,

$$\int_{\partial[f]} \Phi = \int_{\Omega} \Phi(\mathbf{v}_n \lrcorner df) d\mathcal{L}^n;$$

this quantity *does not* depend on a choice of inner product but *does*, obviously, depend on the volume form.

Suppose E is an open subset of Ω whose boundary is a smooth embedded hypersurface. Then $E \in \mathbf{BV}^{loc}(\Omega)$ and

$$\mathbf{M}(\partial[E]) = \mathcal{H}^{n-1}(E);$$

here and in what follows we identify a subset of Ω with its indicator function 1_{Ω} .

Slicing formulae.

Indispensable in the study of functions of bounded variation is the **slicing** (*aka* “**coarea**”) formula:

$$\mathbf{M}(\partial[f] \llcorner B) = \int_{-\infty}^{\infty} \mathbf{M}(\partial[\{f \geq y\}] \llcorner B) d\mathcal{L}^1 y$$

where B is any Borel set. We have generalized this formula as follows. Suppose Φ is a **convex and positive** integrand. Then

$$\int_{\partial[f] \llcorner B} \Phi = \int_{-\infty}^{\infty} \left(\int_{\partial[\{f \geq y\}] \llcorner B} \Phi \right) d\mathcal{L}^1 y$$

where B is any Borel set.

Some convenient notations.

Suppose n is a positive integer and Ω is an open subset of \mathbb{R}^n . We let

$$\mathcal{F}(\Omega) = \mathbf{L}_1(\Omega) \cap \mathbf{L}_\infty(\Omega)$$

and we let

$$\mathcal{M}(\Omega)$$

be the family of Lebesgue measurable subsets of Ω with finite Lebesgue measure. Thus a subset E of Ω belongs to $\mathcal{M}(\Omega)$ if and only if $1_E \in \mathcal{F}(\Omega)$.

The integrand Φ .

We now fix a **positive and convex** integrand

$$\Phi : \bigwedge_{n-1} \mathbb{R}^n \rightarrow [0, \infty).$$

For each $\xi \in \{\Phi = 1\}$ we let

$$\nu(\xi) = \left\{ \psi \in \bigwedge^{n-1} \mathbb{R}^n : \{\Phi = \psi\} \neq \emptyset \text{ and } \psi \leq \Phi \right\}$$

and we let

$$\mathbf{F}(\xi) = \{\eta \in \{\Phi = 1\} : \nu(\xi) = \nu(\eta)\}.$$

Thus $\nu(\xi)$ corresponds to the family of support hyperplanes of the convex set $\{\Phi \leq 1\}$ at ξ . We call $\mathbf{F}(\xi)$ the **face of $\{\Phi \leq 1\}$ at ξ** ; it is elementary that each face is convex and that $\{\Phi \leq 1\}$ is the disjoint union of the family $\{\mathbf{F}(\xi) : \xi \in \{\Phi = 1\}\}$.

Total variation regularization.

Suppose

$$F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}.$$

Given $\epsilon > 0$ we set

$$F_{\Phi, \epsilon}(f) = \epsilon \int_{\partial[f]} \Phi + F(f), \quad f \in \mathbf{BV}(\Omega) \cap \mathcal{F}(\Omega);$$

we call $F_{\Phi, \epsilon}$ a **total variation regularization** of F . We let

$$\mathbf{m}_{\Phi, \epsilon}^{loc}(F)$$

be the set of $f \in \mathbf{BV}(\Omega) \cap \mathcal{F}(\Omega)$ such that

$$F_{\Phi, \epsilon}(f) \leq F_{\Phi, \epsilon}(g)$$

whenever $g \in \mathbf{BV}(\Omega) \cap \mathcal{F}(\Omega)$ and g equals f outside some compact subset of Ω .

Total variation regularization, continued.

Suppose

$$M : \mathcal{M}(\Omega) \rightarrow \mathbb{R}.$$

Given $\epsilon > 0$ we set

$$M_{\Phi, \epsilon}(E) = \epsilon \int_{\partial[E]} \Phi + M(E) \quad \text{for } E \in \mathcal{M}(\Omega);$$

we call $M_{\Phi, \epsilon}$ a **total variation regularization of M** . We let

$$\mathbf{n}_{\Phi, \epsilon}^{loc}(M)$$

be the set of $D \in \mathcal{M}(\Omega)$ such that $M_{\Phi, \epsilon}(D) \leq M_{\Phi, \epsilon}(E)$ whenever $E \in \mathcal{F}(\Omega)$ and $D = E$ outside some compact subset of Ω .

Admissibility.

Suppose

$$F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}.$$

For each $Y \in (0, \infty)$ we let

$$I(F, Y)$$

be the infimum of those $L \in (0, \infty)$ such that

$$|F(f) - F(g)| \leq L \int_{\Omega} |f - g| d\mathcal{L}^n$$

whenever $f, g \in \{h \in \mathcal{F}(\Omega) : \|h\|_{\mathbf{L}_{\infty}(\Omega)} \leq Y\}$.

We say F is **admissible** if $I(F, Y) < \infty$ whenever $0 < Y < \infty$.

Thus F is admissible if F is Lipschitzian with respect to $\|\cdot\|_{\mathbf{L}_1(\Omega)}$ on subsets of $\mathcal{F}(\Omega)$ which are bounded with respect to $\|\cdot\|_{\mathbf{L}_{\infty}(\Omega)}$.

Admissibility for functionals on sets.

Suppose

$$M : \mathcal{F}(\Omega) \rightarrow \mathbb{R}.$$

We let

$$\mathbf{I}(M)$$

be the infimum of those $L \in (0, \infty)$ such that

$$|M(D) - M(E)| \leq L \int_{\Omega} |1_D - 1_E|, \quad D, E \in \mathcal{M}(\Omega).$$

We say M is **admissible** if $\mathbf{I}(M) < \infty$.

The space $\mathcal{C}_\lambda(\Omega)$, $0 \leq \lambda < \infty$, ...

...consists of those sets $D \in \mathcal{M}(\Omega)$ with locally finite perimeter such that

$$\int_{\partial[D] \llcorner K} \Phi \leq \int_{\partial[E] \llcorner K} \Phi + \lambda \int_{\Omega} |1_D - 1_E|$$

whenever $E \in \mathcal{M}(\Omega)$ and K is a compact subset of Ω such that $\mathcal{L}^n(((D \sim E) \cup (E \sim D)) \sim K) = 0$.

Theorem. If $M : \mathcal{M}(\Omega) \rightarrow \mathbb{R}$, M is admissible, $0 < \epsilon < \infty$, and $D \in \mathbf{n}_{\Phi, \epsilon}^{loc}(M)$ then $D \in \mathcal{C}_\lambda(\Omega)$ with $\lambda = \frac{I(M)}{\epsilon}$.

Theorem. If $F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}$, F is admissible, $0 < \epsilon < \infty$, and $f \in \mathbf{m}_{\Phi, \epsilon}^{loc}(F)$ then $\{f > y\} \in \mathcal{C}_\lambda(\Omega)$ with $\lambda = \frac{I(F, \|f\|_{L^\infty(\Omega)})}{\epsilon}$.

Regularity Theorem for $C_\lambda(\Omega)$.

We have prove the following Theorem when $n = 2$.

Theorem. Suppose

$$0 \leq \lambda < \infty \quad \text{and} \quad 0 < \zeta < 1$$

there is

$$\theta \in (0, 1)$$

such that if $D \in C_\lambda(\Omega)$, B is the reduced boundary of D , $a \in B$,

$$0 < R \leq \mathbf{dist}(a, \mathbb{R}^n \sim \Omega) \quad \text{and} \quad \lambda R < \theta$$

and $M = B \cap \mathbf{B}(a, \theta R)$ then M is a graph and for each $b \in B$ there are $\xi \in \mathbf{F}(*\mathbf{n}_D(a))$, $\eta \in \mathbf{F}(*\mathbf{n}_D(b))$ such that

$$|\xi - \eta| \leq \zeta.$$

Locality.

We say $F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}$ is **local** if

$$F(f + g) + F(0) = F(f) + F(g)$$

whenever $f, g \in \mathcal{F}$ and $fg = 0$.

We say $M : \mathcal{M}(\Omega) \rightarrow \mathbb{R}$ is **local** if

$$M(D \cup E) + M(\phi) = M(D) + M(E)$$

whenever $E, F \in \mathcal{M}$ and $D \cap E = \emptyset$.

Locality, continued.

By soft analysis, F is admissible and local if and only if

$$F(f) = F(0) + \int_{\Omega} k(x, f(x)) d\mathcal{L}^n x, \quad f \in \mathcal{F}(\Omega)$$

for some Borel function $k : \Omega \times [0, \infty) \rightarrow \mathbb{R}$ such that $\Omega \ni x \mapsto k(x, 0)$ is bounded and such that for each $Y \in (0, \infty)$ there is a constant L such that

$$|k(x, y) - k(x, z)| \leq L|y - z| \quad \text{for } x \in \Omega \text{ and } y, z \in [0, Y].$$

By soft analysis, M is admissible and local if and only if

$$M(E) = M(\emptyset) + \int_E m(x) d\mathcal{L}^n x, \quad E \in \mathcal{M}(\Omega)$$

for some $m \in \mathbf{L}_{\infty}(\Omega)$.

Representing $F(f)$ in terms of superlevel sets of f .

Suppose $F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}$ is admissible and local. We let

$$I(x, y) = \limsup_{z \downarrow y} \frac{k(x, z) - k(x, y)}{z - y}, \quad (x, y) \in \Omega \times [0, \infty).$$

For each $y \in (0, \infty)$ we let

$$U_y(E) = \int_E I(x, y) d\mathcal{L}^n x \quad \text{whenever } E \in \mathcal{M}(\Omega)$$

and note that U_y is admissible and local.

It is elementary that

$$F(f) = F(0) + \int_0^\infty U_y(\{f > y\}) d\mathcal{L}^1 y \quad \text{for } f \in \mathcal{F}(\Omega).$$

...thus, by the slicing (*aka* “coarea”) formula,

$$F_{\Phi, \epsilon}(f) = F(0) + \int_0^\infty \epsilon \left(\int_{\partial\{f > y\}} \Phi \right) + U_y(\{f > y\}) d\mathcal{L}^1 y$$

for $f \in \mathbf{BV}(\Omega) \cap \mathcal{F}(\Omega)$.

Zooming in on the value.

Theorem. Suppose $F : \mathcal{F}(\Omega) \rightarrow \mathbb{R}$ is admissible, local and convex; Φ is positive and convex; $0 < \epsilon < \infty$ and

$$f \in \mathbf{m}_{\Phi, \epsilon}^{loc}(F).$$

Then

$$\{f > y\} \in \mathbf{n}_{\Phi, \epsilon}^{loc}(U_y) \quad \text{whenever } 0 < y < \infty.$$

Special cases of this Theorem appear in works of Chambolle and Chan-Esedoglu. As it turns out, minimizers for $(U_y)_\epsilon$, $0 < y < \infty$, are easier to understand than minimizers of $F_{\Phi, \epsilon}$.

Conversely...

Theorem. Suppose $F : \mathcal{M}(\Omega) \rightarrow \mathbb{R}$ is admissible, local and convex; Φ is positive and convex; $0 < \epsilon < \infty$; and G is an $\mathcal{L}^n \times \mathcal{L}^1$ measurable subset of $\Omega \times (0, \infty)$ such that

$$\{x : (x, y) \in G\} \in \mathbf{n}_{\Phi, \epsilon}^{loc}(U_y) \quad \text{for } \mathcal{L}^1 \text{ almost all } y$$

and

$$f(x) = \mathcal{L}^1(\{y : (x, y) \in G\}) \quad \text{for } x \in \Omega.$$

Then

$$f \in \mathbf{m}_{\Phi, \epsilon}^{loc}(F).$$

Denoising s .

For the remainder of this talk, $n = 2$, $\Omega = \mathbb{R}^2$ and

$$\gamma : \mathbb{R} \rightarrow [0, \infty)$$

is such that $\gamma(0) = 0$, $\gamma(y) > 0$ if $y \in \mathbb{R} \setminus \{0\}$ and such that γ is convex. Of particular interest are

$$\gamma(y) = \frac{y^2}{2} \quad \text{and} \quad \gamma(y) = |y| \quad \text{for } y \in \mathbb{R}.$$

Suppose

$$s \in \mathcal{M}(\mathbb{R}^2);$$

s could be a grayscale image which we wish to denoise.
For $f \in \mathcal{F}(\mathbb{R}^2)$ let

$$F(f) = \int \gamma(f(x) - s(x)) \, d\mathcal{L}^2x;$$

Obviously, $F(f) = 0$ iff f and s agree almost everywhere.
Moreover, F is admissible, local and convex.

β , r and s .

Let

$$\beta(y) = \limsup_{z \downarrow y} \frac{\gamma(z) - \gamma(y)}{z - y} \quad \text{for } y \in \mathbb{R}.$$

Note that β is nonincreasing and negative on $(-\infty, 0)$ and nondecreasing and positive on $(0, \infty)$. For example, if $\gamma(y) = |y|$, $y \in \mathbb{R}$, then

$$\beta(y) = \begin{cases} -1 & \text{if } -\infty < y < 0, \\ 1 & \text{if } 0 \leq y < \infty \end{cases}$$

and if $\gamma(y) = y^2/2$, $y \in \mathbb{R}$, then

$$\beta(y) = y \quad \text{for } y \in \mathbb{R}.$$

For each $y \in (0, \infty)$ we have

$$U_y(E) = \int \beta(y - s(x)) d\mathcal{L}^2x \quad \text{for } E \in \mathcal{M}(\mathbb{R}^2).$$

Binary images.

We fix a compact subset

S

of \mathbb{R}^2 with $\mathcal{L}^2(S) > 0$ and let $s = 1_S$. We have not yet attempted to extend the work which follows for more general s . We let

$$\mathbf{r}(y) = -\frac{\epsilon}{\beta(y-1)} \quad \text{and we let} \quad \mathbf{s}(y) = \frac{\epsilon}{\beta(y)} \quad \text{for } 0 < y < 1;$$

note that \mathbf{r} is nondecreasing and \mathbf{s} is nonincreasing.

The functionals $M_{r,s}$.

For reasons which will shortly become obvious, we let $P = (0, \infty) \times (0, \infty)$ and for each $(r, s) \in P$ we let

$$M_{r,s}(E) = -\frac{1}{r}\mathcal{L}^2(E \cap S) + \frac{1}{s}\mathcal{L}^2(E \sim S) \quad \text{for } E \in \mathcal{M}(\mathbb{R}^2).$$

Note that

$$M_{r,s}(\emptyset) = 0.$$

Whenever $0 < y < 1$ we have

$$\frac{1}{\epsilon}U_y = M_{r(y),s(y)} \quad \text{for } 0 < y < 1.$$

so

$$\mathbf{n}_{\Phi,\epsilon}^{loc}(U_y) = \mathbf{n}_{\Phi,1}^{loc}(M_{r(y),s(y)}).$$

From an earlier result it follows that...

...if

v

is a function with domain $(0, 1)$ and values in $\mathcal{M}(\mathbb{R}^2)$ such that $\{(x, y) : x \in v(y)\}$ is \mathcal{L}^2 measurable;

$$v(y) \in \mathbf{n}_1^{loc}(M_{r(y), s(y)}) \quad \text{for } 0 < y < 1;$$

and

$$f(x) = \mathcal{L}^1(\{y \in (0, 1) : x \in v(y)\}) \quad \text{for } x \in \mathbb{R}^2$$

then

$$f \in \mathbf{m}_{\Phi, \epsilon}^{loc}(F).$$

Moreover, all minimizers arise in this way.

Thus *if we can determine $\mathbf{n}_{\Phi, 1}^{loc}(M_{r, s})$ for $(r, s) \in P$ we have determined $\mathbf{m}_{\Phi, \epsilon}^{loc}(F)$ for any γ .*

The function Ψ and the sets Q and N .

For each $(r, s) \in P$ we let

$$\Psi(r, s) = \inf \left\{ \int_{\partial[E]} \Phi + M_{r,s}(E) : E \in \mathcal{M}(\mathbb{R}^2) \right\}.$$

We let

Q

be the set of those $(r, s) \in P$ such that $\mathbf{n}_1^{loc}(M_{r,s})$ contains a set of positive measure and we let

N

be the set of those $(r, s) \in P$ such that $\mathbf{n}_1^{loc}(M_{r,s})$ has **two or more** essentially distinct members of positive measure.

More about Q .

Theorem. Q is closed and there is a nondecreasing function $q : (0, \infty) \rightarrow (0, \infty)$ such that

$$Q = \{(r, s) \in P : r \leq q(s)\}.$$

Moreover, for any $(r, s) \in P$ we have

$$r < q(s) \Leftrightarrow \Psi(r, s) < 0.$$

More about N .

For each $\eta > 0$ let

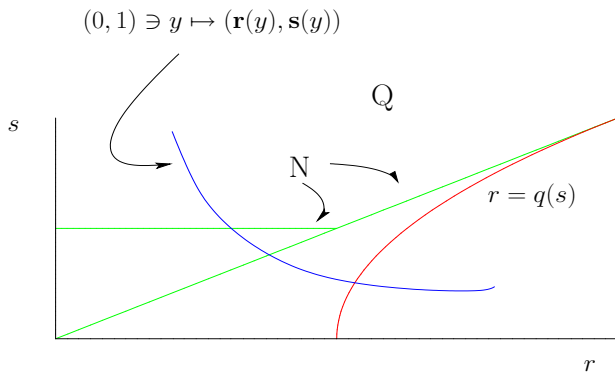
$$N_\eta = \{(r, s) \in N : \Psi(r, s) \leq -\eta\}.$$

Theorem Suppose (r, s) is an accumulation point of N_η . Then

$$\mathbf{Tan}(N_\eta, (r, s)) \subset ([0, \infty) \times [0, \infty)) \cup ((-\infty, 0] \times (-\infty, 0]).$$

This implies that N is $(\mathcal{H}^1, 1)$ rectifiable.

The basic picture.



When S is convex.

For the next ten slides we suppose $\Phi = \text{std}$.

For each $r \in (0, \infty)$ let

$$T_r = \cup \{ \mathbf{B}(c, r) : \mathbf{B}(c, r) \subset S \}$$

and let

$$\Gamma(r) = \mathbf{M}(\partial[T_r]) - \frac{1}{r} \mathcal{L}^2(T_r).$$

Theorem. Γ is increasing and locally Lipschitzian. Moreover,

$$Q = \{(r, s) \in P : \Gamma(r) \leq 0\}.$$

Two squares.

Now let

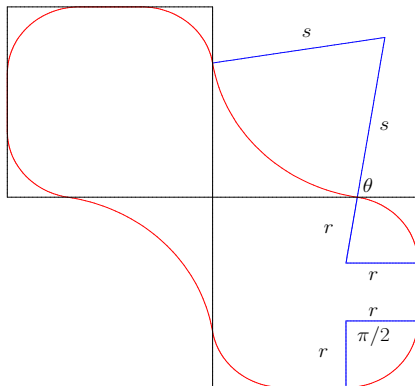
$$S = ([0, 1] \times [0, -1]) \cup ([-1, 0] \times [0, 1]).$$

We will describe $\mathbf{n}_1^{loc}(M_{r,s})$, $(r, s) \in P$ in detail.

The sets $F_{r,s}$, $r + s > 1$.

Here $r = .35$ and $s = .85$.

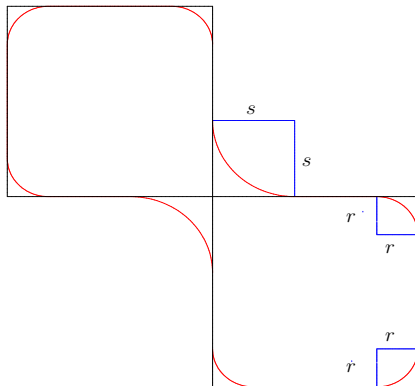
$$\theta = \Theta(r, s), \quad r + s > 1;$$



The sets $G_{r,s}$, $r + s \leq 1$.

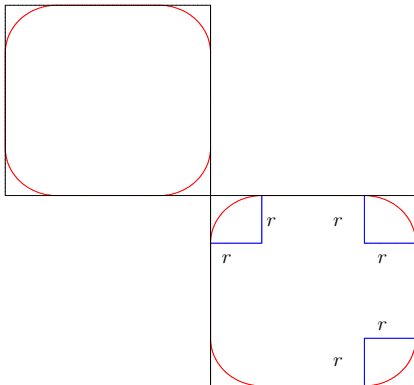
Here $r = .2$ and $s = .4$. $r + s \leq 1$

The blue corner angles are all right angles.



The sets H_r , $r \leq 1/2$.

Here $r = .2$. The blue angles are right angles.

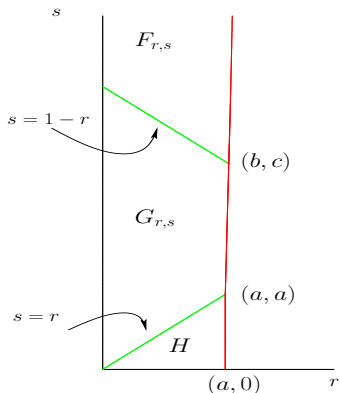


The whole story for two squares.

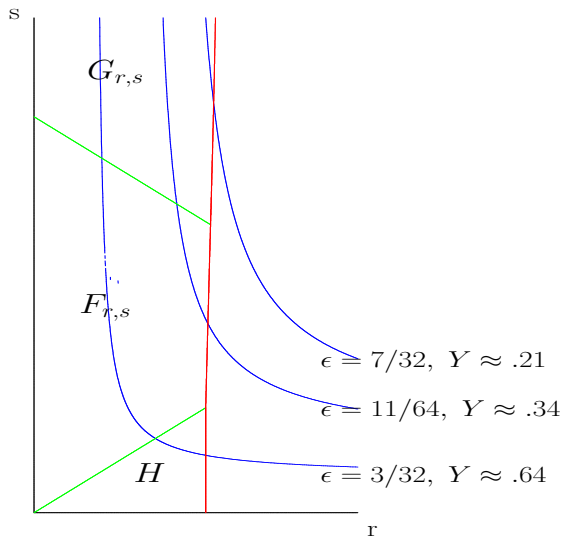
$$a = \frac{\sqrt{2-\pi}}{4-\pi} \approx .2650794522$$

$$b = \frac{\sqrt{\pi^2+56\pi+16}-(\pi+12)}{16-4\pi} \approx 0.2725985674$$

$$c = \frac{\sqrt{\pi^2+56\pi+16}-5\pi+4}{16-4\pi} \approx 0.7274014326$$



The various possibilities.



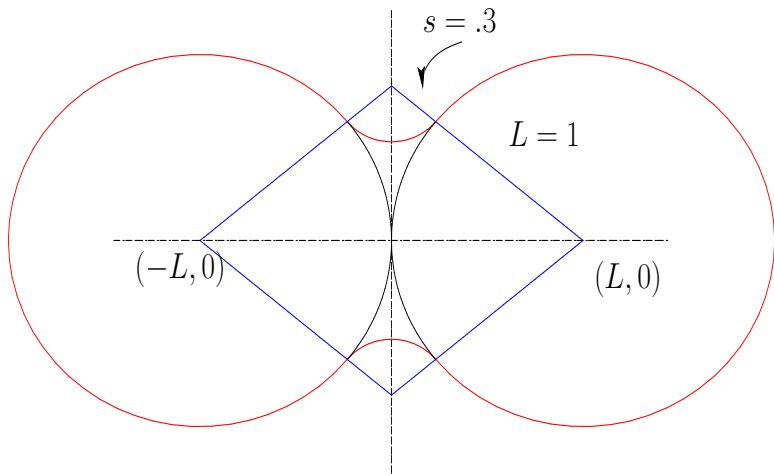
Two circles.

Suppose $1 \leq L < \infty$. Let $c_{\pm} = (\pm L, 0)$ and let

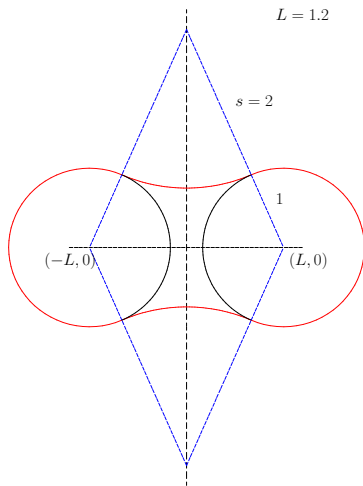
$$S = \mathbf{B}(c_-, 1) \cup \mathbf{B}(c_+, 1).$$

We will describe $\mathbf{n}_1^{loc}(M_{r,s})$, $(r, s) \in P$, in detail.

The sets F_s , $s \geq 2L/(L^2 + 1)$.



The sets F_s , $s \geq 2L/(L^2 + 1)$.



The functions Γ_F and Γ_G .

Let

$$\Gamma_F(r, s) = \int_{\partial[F_s]} \Phi + M_{r,s}(F_s), \quad 0 < r < \infty, \quad \frac{2L}{L^2 + 1} < s < \infty$$

and let

$$\Gamma_G(r, s) = \int_{\partial[S]} \Phi + M_{r,s}(S), \quad (r, s) \in P.$$

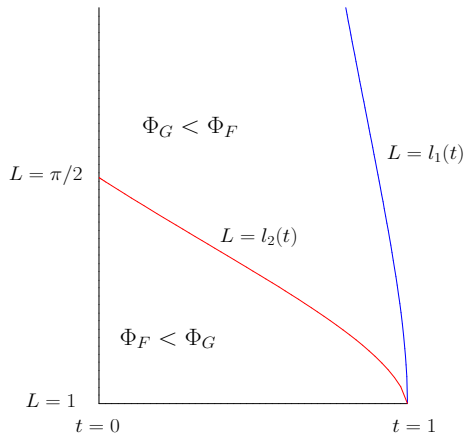
Theorem. Suppose $E \in \mathbf{n}_1^{loc}(M_{r,s})$. Then *either* $E = F_s$ *or* $E = S$.
Well, not exactly...

The winners; here $t = L/(1 + s)$.

$$l_1(t) = \frac{1 + \sqrt{1 - t^2}}{t}$$

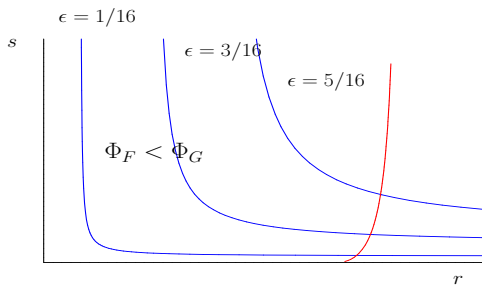
$$l_2(t) = \frac{t(1 + \sqrt{1 - \beta(t)})}{\beta(t)}$$

$$\beta(t) = \frac{2}{\pi}(\arcsin(t) + t\sqrt{1 - t^2})$$



Two circles touching.

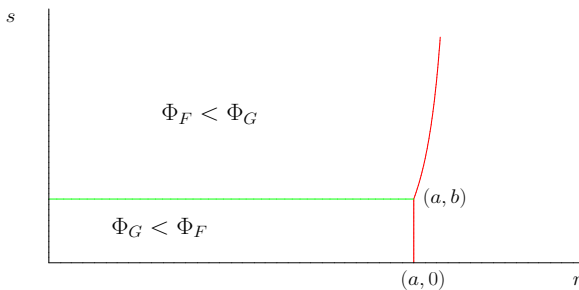
$$L = 1$$



Two circles separated.

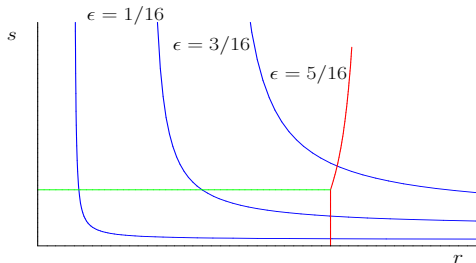
$$L = 1.2$$

$$a = 1/2, \quad b = 0.5646473918$$



Two circles separated.

$$L = 1 \quad \gamma(y) = \frac{y^2}{2}$$



Wulff shapes.

Let

$$\Phi^W : \mathbb{R}^n \rightarrow [0, \infty)$$

be defined by setting

$$\Phi^W(v) = \sup\{\langle v \wedge \xi, \mathbf{V}^n \rangle : \xi \in \{\Phi = 1\}\}.$$

It is evident that Φ^W is positively homogeneous, positive away from zero and convex. Let

$$W_\Phi = \{\Phi^W \leq 1\}.$$

The closed convex set W_Φ is called the **Wulff shape associated to Φ (and \mathbf{V}^n)**.

What a minimizer looks like.

We now suppose

$$E \in \mathbf{n}_1^{loc}(M_{r,s}).$$

From our Regularity Theorem it follows that $[E] = [\mathbf{spt}[E]]$ and that there is one and only one finite disjoint family

$$\mathcal{C}$$

of simple oriented closed Lipschitz curves such that

$$\partial[E](\omega) = \sum_{C \in \mathcal{C}} \int_C \omega \quad \text{for } \omega \in \mathcal{D}^1(\mathbb{R}^2).$$

Moreover, the oscillation of the tangent to these curves is controlled in an *a priori* manner by Φ , r and s .

The view from the inside.

Suppose

$$b \in C \cap \mathbf{int} S \quad \text{for some } C \in \mathcal{C}.$$

Then the connected component of b in $C \cap \mathbf{int} S$ is for some $c \in \mathbb{R}^2$ a subset of

$$B = c + rW_\phi.$$

Moreover, $\mathbf{spt} [E]$ near $C \cap \mathbf{int} S$ lies on the *inside* of B , and the aforementioned connected component lies in an *open half plane whose boundary contains c* .

The view from the outside.

Suppose

$$b \in C \cap \mathbf{int}(\mathbb{R}^2 \sim S) \text{ for some } C \in \mathcal{C}.$$

Then the connected component of b in $C \cap \mathbf{int}(\mathbb{R}^2 \sim S)$ is for some $c \in \mathbb{R}^2$ a subset of

$$B = c + sW_\phi.$$

Moreover, $\mathbf{spt}[E]$ near $C \cap \mathbf{int}(\mathbb{R}^2 \sim S)$ lies on the *outside* of B , and the aforementioned connected component lies in an *open half plane* whose boundary contains c .

Two squares, again.

Suppose

$$\Phi(x) = \max\{|x_1|, |x_2|\} \quad \text{for } x \in \mathbb{R}^2.$$

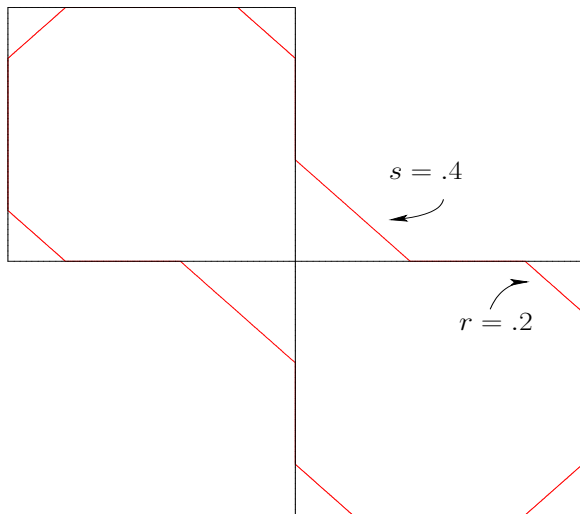
Then

$$W_\Phi = \{x \in \mathbb{R}^2 : |x_1| + |x_2| \leq 1\}.$$

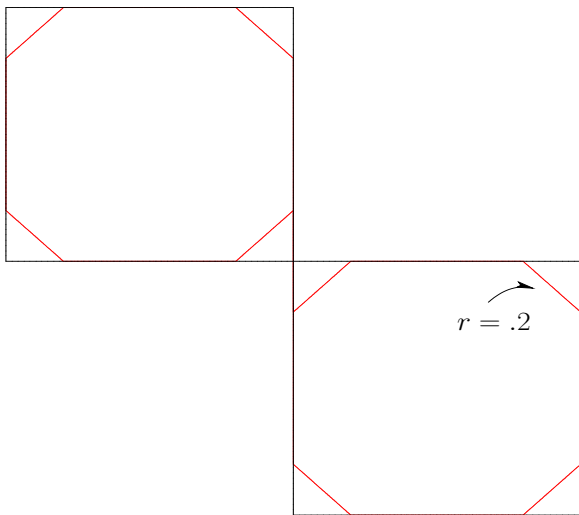
Let




$$S = ([0, 1] \times [0, -1]) \cup ([-1, 0] \times [0, 1]).$$

The sets $G_{r,s}$.



The sets H_r .



-  W. K. Allard: *Total variation regularization for image denoising; I. Geometric theory*. SIAM Journal on Mathematical Analysis, **39**, (2007), p. 1150-1190.
-  W. K. Allard: *Total variation regularization for image denoising; II. Examples*. SIAM Journal on Imaging Sciences, **1**, (2008), p. 400-417.
-  W. K. Allard: *Total variation regularization for image denoising; I. Geometric theory*. SIAM Journal on Imaging Sciences, **2**, (2007), p. 532-568.