

Algebraic Derivation of "Broken $\mathbb{Z}_N$ -Symmetric" Solutions for the Star-Triangle Relations

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1. Introduction. Recently remarkable progress is made in the theory of exactly solvable lattice models. Among them well-studied are the models defined by the quantum R- matrices which is the solution of the Yang - Baxter equation (YBE) related to the q -analogue of the enveloping algebra $U_q(\mathfrak{g})$ [J]. Meanwhile there are solutions for the YBE or the STR whose algebraic background were not clarified so far. Fateev -Zamolodchikov's $\mathbb{Z}_N$ - symmetric model[FZ], chiral Potts model [AMPTY][BPA] and Kashiwara - Miwa's broken $\mathbb{Z}_N$ -symmetric model*[KM] are for example. In these three solutions the latter two are mutually different extension of the first one: while chiral Potts is defined by the coordinate functions of some curve of genus > 1 , broken $\mathbb{Z}_N$ is defined by the elliptic theta functions.

Recently Bazhanov and Stroganov observed that the chiral Potts can be obtained as a solution of some linear equation related to the 6- vertex model [BS]. In this note, sketching [HY], we will show that the broken $\mathbb{Z}_N$ model can be obtained as a descendant of the 8-vertex model in the same manner. For that purpose we use Sklyanin's L- operator for the 8- vertex model instead of the L- operator which is given and used by [BZ] to get the chiral Potts. In our derivation a new discrete parameter $N' \in \mathbb{Z}$, $(N, N')=1$ (coprime), which is involved in Sklyanin's L naturally come into the broken $\mathbb{Z}_N$ model.

(*: This is an extension of $\mathbb{Z}_N$ - symmetric solution of the STR but not $\mathbb{Z}_N$ symmetric, hence the name. ($\mathbb{Z}_N = \mathbb{Z}/N\mathbb{Z}$.) In [KM] they found

this solution through computer experiments.)

2. Sklyanin algebra. As is similar to the method of [BZ] for chiral Potts, we will derive the broken $\mathbb{Z}_N$ - model as the solution

$S \in \text{End}(\mathbb{C}^N \otimes \mathbb{C}^N)$ for the equation

$$1) \quad S^{12} L^{02}(u) L^{01}(v) = L^{01}(v) L^{02}(u) S^{12} \quad \text{on} \quad V_0 \otimes V_1 \otimes V_2, \\ \text{where} \quad V_0 = \mathbb{C}^2, \quad V_1 = V_2 = \mathbb{C}^N, \quad L^{01}(v) = L(v) \otimes \text{id}_{V_2} \text{ etc.} \quad \text{Here } L$$

$\in \text{End}(\mathbb{C}^N \otimes \mathbb{C}^2)$ is a given L- operator which satisfies

$$2) \quad R^{12}(u-v) L^{02}(u) L^{01}(v) = L^{01}(v) L^{02}(u) R^{12}(u-v) \quad \text{on} \quad V_0 \otimes V_1 \otimes V_2, \\ \text{where} \quad V_0 = \mathbb{C}^N, \quad V_1 = V_2 = \mathbb{C}^2 \quad \text{and} \quad R(u) \in \text{End}(\mathbb{C}^2 \otimes \mathbb{C}^2) \quad \text{is the} \\ \text{Baxter's 8- vertex solution for YBE [Fig.0]}$$

$$3) \quad R^{12}(u-v) R^{02}(u) R^{01}(v) = R^{01}(v) R^{02}(u) R^{12}(u-v) \quad \text{on} \quad \mathbb{C}^2 \otimes \mathbb{C}^2 \otimes \mathbb{C}^2.$$

We will solve 1) for Sklyanin's L- operator, which we recall now [S1,S2]. By means of the Pauli matrices

$$\sigma_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \sigma_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_2 = \sqrt{-1} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

we can write Baxter's solution as $R(u) = \sum_{\alpha=0}^3 w_{\alpha}(u) \sigma_{\alpha} \otimes \sigma_{\alpha}$, where

$$(w_0, w_1, w_2, w_3) = (H(u+\eta)/H(\eta), H_1(u+\eta)/H_1(\eta), \Theta_1(u+\eta)/\Theta_1(\eta), \Theta(u+\eta)/\Theta(\eta)) \\ \text{with } H(u) = 2q^{1/4} \sin \frac{\pi u}{2I} \prod_{n=1}^{\infty} (1-2q^{2n} \cos \pi u/I + q^{4n}) (1-q^{2n}) \quad (q=e^{-\pi I'/I}), \\ \Theta(u) = -\sqrt{-1} e^{\sqrt{-1}\pi u/2I} H(u+\sqrt{-1}I'), \quad H_j(u) := H(u+jI), \quad \Theta_j(u) := \Theta(u+jI) \quad [B]$$

Sklyanin's observation. Let w_{α} are as above and $S_{\alpha} \in \text{Mat}(\mathbb{C}^N)$.

Then $L(u) = \sum_{\alpha=0}^3 w_{\alpha}(u) \sigma_{\alpha} \otimes S_{\alpha}$ satisfies 2) if and only if the following relations (*without the spectral parameter* u) hold:

$$4) \quad [S_0, S_{\alpha}]_+ = -\sqrt{-1} [S_{\beta}, S_{\gamma}]_-, \quad [S_0, S_{\alpha}]_- = \sqrt{-1} J_{\beta\gamma} [S_{\beta}, S_{\gamma}]_+.$$

Here $(\alpha, \beta, \gamma) = (123), (231), (312)$ (so there are 6 relations) and $J_{\beta\gamma} = -J_{\gamma\beta}$, $(J_{12}, J_{23}, J_{13}) = (H\Theta(\eta)^2/H_1\Theta_1(\eta)^2, HH_1(\eta)^2/\Theta\Theta_1(\eta)^2, H\Theta_1(\eta)^2/\Theta H_1(\eta)^2)$. ■

We call the associative algebra defined by 4 generators S_{α} with defining relations 4) the **Sklyanin algebra**. A representation of the Sklyanin algebra gives an L- operator by the above. Sklyanin's own representation of "series b" [S2] provides the L- operator that we use here, which has continuous parameters γ, λ, Δ and is given by

$$S_{\alpha} = S_{\alpha}(\gamma, \lambda, \Delta) \in \text{End } \mathbb{C}^N, \quad \mathbb{C}^N = \bigoplus_{a=0}^{N-1} \mathbb{C} \varphi_a, \quad \varphi_a = \varphi_{a \bmod N}$$

$$5) \quad S_{\alpha} \varphi_a := \Theta(A_a)^{-1} \{ \Delta s_{\alpha}(A_a + \eta - \lambda) \varphi_{a+1} + \Delta^{-1} \varepsilon_{\alpha} s_{\alpha}(A_a - \eta + \lambda) \varphi_{a-1} \},$$

where $A_a = 2\gamma + 2a\eta$, $\varepsilon_0 = -\varepsilon_1 = \varepsilon_2 = \varepsilon_3 = 1$, $s_0(u) = H(\eta)\Theta_1(u)$,
 $s_1(u) = -\sqrt{-1} H_1(\eta)\Theta(u)$, $s_2(u) = \Theta_1(\eta)H(u)$, $s_3(u) = \Theta(\eta)H_1(u)$.

This representation is well defined iff $\eta = 2iN'/N$ for some $N' \in \mathbb{Z}$, and can be considered as an elliptic analog of the "cyclic" representations [DK] of the algebra $U_q(\mathfrak{sl}(2))$ at $q = \exp 2\pi i N'/N$.

3. "Localization" of eq. 1). The matrix elements of the L -operator associated to the representation 5) factor as [Fig.1]:

$$L(u) = (L(u)_{jb}^{ia})_{(jb), (ia)} \left[\begin{matrix} i, j = 0, 1 \\ a, b = 0, \dots, N-1 \end{matrix} \right], \quad L(u)_{jb}^{ia} = K(u)_{jb}^a K(u)_{b}^{ia}.$$

According to this, we assume that S is of the form [Fig.2]

$$6) \quad S(u, v)_{a, b}^{a, b} = W(u, v)_{ab} W(u, v)_{b, a}, \quad \bar{W}(u, v)_{b, a}^a, \quad \bar{W}(u, v)_{a, b}^b.$$

(So W 's and $\bar{W}$'s [Fig.3] are unknown.) Then by [Fig.6] we find

Proposition ("Localization"). *The following 7) and 8) are sufficient for S of the form 6) to satisfy the equation 1) :*

$$7) \quad W(u, v)_{dc} \sum_{j=0}^1 K(u)_{jd}^a K(v)_{c}^{jb} = W(u, v)_{ab} \sum_{j=0}^1 K(v)_{jd}^a K(u)_{c}^{jb} \quad [\text{Fig.4}],$$

$$8) \quad \sum_{b=0}^{N-1} K(u)_{jc}^b K(v)_{c}^{ib} \bar{W}(u, v)_{b, a}^a = \sum_{b=0}^{N-1} \bar{W}(u, v)_{c, b}^b K(v)_{jc}^b K(u)_{b, a}^{ia} \quad [\text{Fig.5}]. \blacksquare$$

4. Theorem[HY]. *A) The equation 7 (resp. 8) have a nontrivial solution if and only if the following 9 (resp. 10) is satisfied:*

$$9) \quad \lambda \in \mathbb{Z} \cdot 2I / (2, N), \quad 2\gamma \in \mathbb{Z}\eta + \mathbb{Z}I.$$

$$10) \quad \lambda \in \mathbb{Z}I, \quad 2\gamma \in \mathbb{Z}\eta + \mathbb{Z}I, \quad \Delta^{2N} = 1.$$

Under these conditions, up to W_{00} the solution is determined by

$$\begin{aligned} \frac{W(u, v)_{a+1, b+1}}{W(u, v)_{a, b}} &= \frac{\Theta_1(2\gamma + (a+b+1)\eta - \lambda - t)}{\Theta_1(2\gamma + (a+b+1)\eta - \lambda + t)}, \\ \frac{W(u, v)_{a+1, b-1}}{W(u, v)_{a, b}} &= \frac{H_1((a-b+1)\eta - \lambda - t)}{H_1((a-b+1)\eta - \lambda + t)} \quad (t = (u-v)/2), \\ \bar{W}((\eta - \lambda - I) - u)_{a, b}^b &= (\sqrt{-1}^{-\lambda/I} \Delta^{N-1})^{b-a} \Theta(A_a) W(u)_{a, b}, \end{aligned}$$

where $W((u-v)/2) = W(u, v)$, $\bar{W}((u-v)/2) = \bar{W}(u, v)$.

B) If $(N, N')=1$, then the STR hold : for some scalar function ρ ,

$$\sum_{d=0}^{N-1} \bar{W}(u-v)_{c, d}^d W(u-w)_{ad} \bar{W}(v-w)_{d, c}^b = \rho W(v-w)_{ac} \bar{W}(u-w)_{c, b}^b W(u-v)_{ab} \quad [\text{Fig.7}]. \blacksquare$$

Note that the STR for W , $\bar{W}$ imply the YBE 3) for S of 6)[Fig.8].

Theorem A is shown by direct calculation. To show B, braid manipulations like [Figs.9,10] give enough relations to reduce the problem to the Schur's Lemma for the Sklyanin algebra representations.

For certain parameters, W and $\bar{W}$ reduce to the solution of STR in [KM]. As in their case[JMO], we expect that the 1 point function of the model (defined by W , $\bar{W}$) relates to affine Lie algebra characters.

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Fig.0

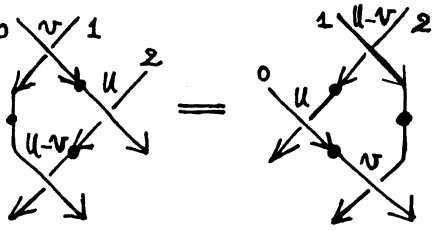


Fig.1

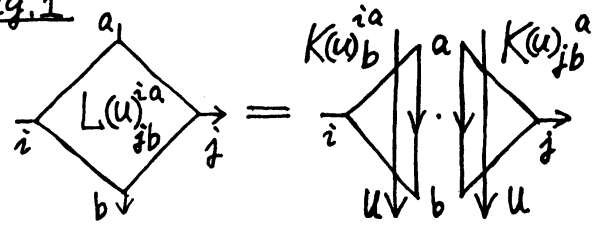


Fig.2

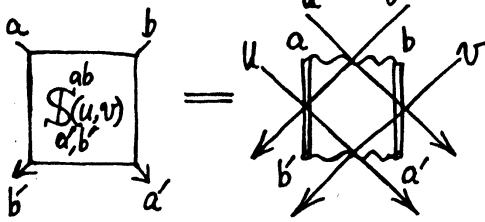


Fig.3

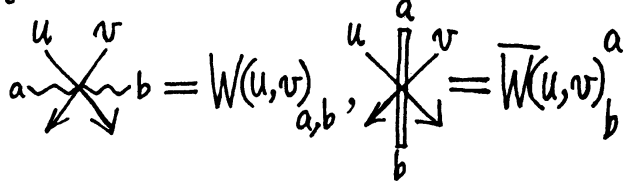


Fig.4

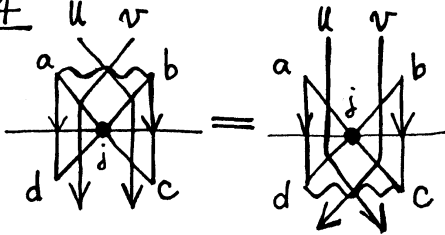


Fig.5

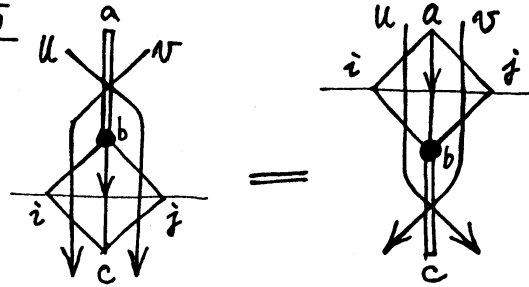


Fig.6

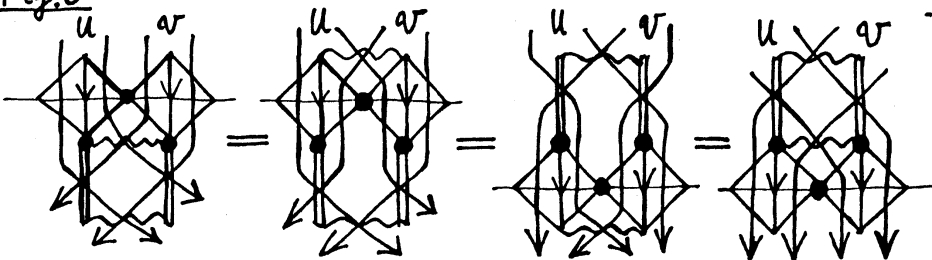


Fig.7

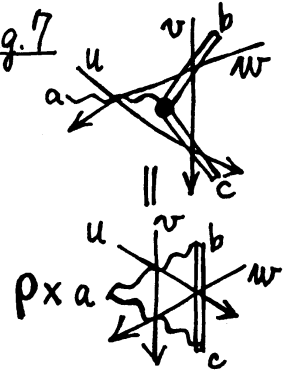


Fig.8

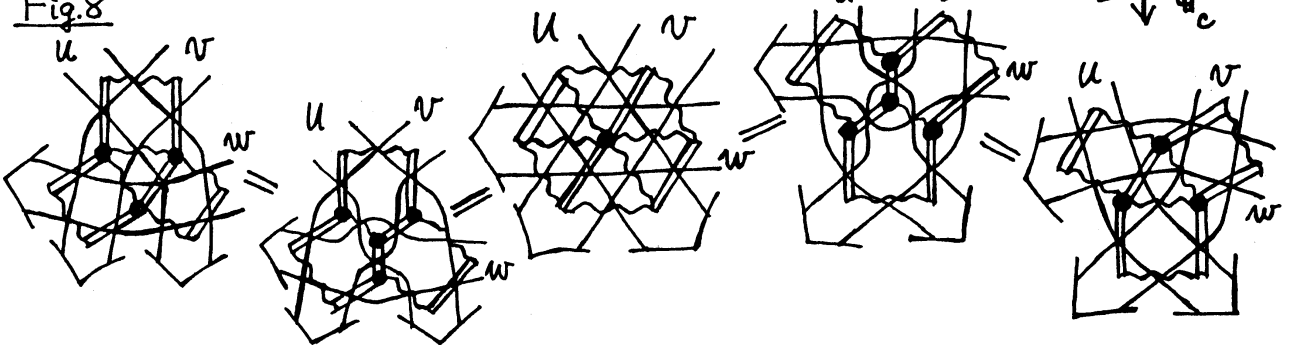


Fig.9

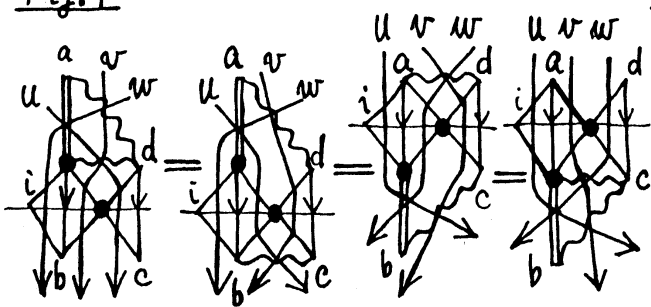


Fig.10

